

NEHRU COLLEGE OF ENGINEERING AND RESEARCH CENTRE (NAAC Accredited)



(Approved by AICTE, Affiliated to APJ Abdul Kalam Technological University, Kerala)

DEPARTMENT OF ELECTRONICS & COMMUNICATION ENGINEERING

COURSE MATERIALS



EC 301: DIGITAL SIGNAL PROCESSING

VISION OF THE INSTITUTION

To mould true citizens who are millennium leaders and catalysts of change through excellence in education.

MISSION OF THE INSTITUTION

NCERC is committed to transform itself into a center of excellence in Learning and Research in Engineering and Frontier Technology and to impart quality education to mould technically competent citizens with moral integrity, social commitment and ethical values.

We intend to facilitate our students to assimilate the latest technological know-how and to imbibe discipline, culture and spiritually, and to mould them in to technological giants, dedicated research scientists and intellectual leaders of the country who can spread the beams of light and happiness among the poor and the underprivileged.

ABOUT DEPARTMENT

♦ Established in: 2002

♦ Course offered: B.Tech in Electronics and Communication Engineering

M.Tech in VLSI

- ♦ Approved by AICTE New Delhi and Accredited by NAAC
- ♦ Affiliated to the University of Dr. A P J Abdul Kalam Technological University.

DEPARTMENT VISION

Providing Universal Communicative Electronics Engineers with corporate and social relevance towards sustainable developments through quality education.

DEPARTMENT MISSION

- 1) Imparting Quality education by providing excellent teaching, learning environment.
- 2) Transforming and adopting students in this knowledgeable era, where the electronic gadgets (things) are getting obsolete in short span.
- 3) To initiate multi-disciplinary activities to students at earliest and apply in their respective fields of interest later.
- 4) Promoting leading edge Research & Development through collaboration with academia & industry.

PROGRAMME EDUCATIONAL OBJECTIVES

PEOI. To prepare students to excel in postgraduate programmes or to succeed in industry / technical profession through global, rigorous education and prepare the students to practice and innovate recent fields in the specified program/ industry environment.

PEO2. To provide students with a solid foundation in mathematical, Scientific and engineering fundamentals required to solve engineering problems and to have strong practical knowledge required to design and test the system.

PEO3. To train students with good scientific and engineering breadth so as to comprehend, analyze, design, and create novel products and solutions for the real life problems.

PEO4. To provide student with an academic environment aware of excellence, effective communication skills, leadership, multidisciplinary approach, written ethical codes and the lifelong learning needed for a successful professional career.

PROGRAM OUTCOMES (POS)

Engineering Graduates will be able to:

- 1. **Engineering knowledge**: Apply the knowledge of mathematics, science, engineering fundamentals, and an engineering specialization to the solution of complex engineering problems.
- 2. **Problem analysis**: Identify, formulate, review research literature, and analyze complex engineering problems reaching substantiated conclusions using first principles of mathematics, natural sciences, and engineering sciences.
- 3. **Design/development of solutions**: Design solutions for complex engineering problems and design system components or processes that meet the specified needs with appropriate consideration for the public health and safety, and the cultural, societal, and environmental considerations.
- 4. **Conduct investigations of complex problems**: Use research-based knowledge and research methods including design of experiments, analysis and interpretation of data, and synthesis of the information to provide valid conclusions.
- 5. **Modern tool usage**: Create, select, and apply appropriate techniques, resources, and modern engineering and IT tools including prediction and modeling to complex engineering activities with an understanding of the limitations.
- 6. **The engineer and society**: Apply reasoning informed by the contextual knowledge to assess societal, health, safety, legal and cultural issues and the consequent responsibilities relevant to the professional engineering practice.
- 7. **Environment and sustainability**: Understand the impact of the professional engineering solutions in societal and environmental contexts, and demonstrate the knowledge of, and need for sustainable development.
- 8. **Ethics**: Apply ethical principles and commit to professional ethics and responsibilities and norms of the engineering practice.
- 9. **Individual and team work**: Function effectively as an individual, and as a member or leader in diverse teams, and in multidisciplinary settings.
- 10. **Communication**: Communicate effectively on complex engineering activities with the engineering community and with society at large, such as, being able to comprehend and write effective reports and design documentation, make effective presentations, and give and receive clear instructions.
- 11. **Project management and finance**: Demonstrate knowledge and understanding of the engineering and management principles and apply these to one's own work, as a member and leader in a team, to manage projects and in multidisciplinary environments.

12. **Life-long learning**: Recognize the need for, and have the preparation and ability to engage in independent and life-long learning in the broadest context of technological change.

PROGRAM SPECIFIC OUTCOMES (PSO)

PSO1: Ability to Formulate and Simulate Innovative Ideas to provide software solutions for Real-time Problems and to investigate for its future scope.

PSO2: Ability to learn and apply various methodologies for facilitating development of high quality

System Software Tools and Efficient Web Design Models with a focus on performance optimization.

PSO3: Ability to inculcate the Knowledge for developing Codes and integrating hardware/software

products in the domains of Big Data Analytics, Web Applications and Mobile Apps to create innovative career path and for the socially relevant issues.

COURSE OUTCOMES EC 301

	SUBJECT CODE: EC 308						
	COURSE OUTCOMES						
C301.1	State and prove the fundamental properties and relations relevant to DFT						
	and solve basic problems involving DFT based filtering methods						
C301.2	Compute DFT and IDFT using DIT and DIF radix-2 FFT algorithms						
C301.3	Design linear phase FIR filters and IIR filters for a given specification						
C301.4	Illustrate the various FIR and IIR filter structures for the realization of the						
	given system function						
C301.5	Explain the architecture of DSP processor (TMS320C67xx) and the finite						
	word length effects						
C301.6	Explain the basic multi-rate DSP operations decimation and interpolation in						
	both time and frequency domains using supported mathematical equations						

MAPPING OF COURSE OUTCOMES WITH PROGRAM OUTCOMES

CO'S	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12
C301.1	3	3	3	3	3	3			2	1		
C301.2	3	3	3	3	3	3			2	1		
C301.3	3	3	3	3	3	3			2	1		
C301.4	3	3	3	3	3	3			2	1		
C301.5	3	3	3	3	3	3			2	1		

C301.6	3	3	3	3	3	3		2	1	
C301	3	3	3	3	3	3		2	1	

CO'S	PSO1	PSO2	PSO3
C301.1	3	3	1
C301.2	3	3	1
C301.3	3	3	1
C301.4	3	3	1
C301.5	3	3	1
C301.6	3	3	1
C301	3	3	1

SYLLABUS

COURSE			YEAR OF
CODE	COURSE NAME	L-T-P-C	INTRODUCTION
EC301	Digital Signal Processing	3-1-0-4	2016

Prerequisite: EC 202 Signals & Systems

Course objectives:

- To provide an understanding of the principles, algorithms and applications of DSP
- To study the design techniques for digital filters
- 3. To give an understanding of Multi-rate Signal Processing and its applications
- 4. To introduce the architecture of DSP processors

Syllabus

Discrete Fourier Transform and its Properties, Linear Filtering methods based on the DFT, Frequency analysis of signals using the DFT, Computation of DFT, FFT Algorithms, IDFT computation using Radix-2 FFT Algorithms, Efficient computation of DFT of two real sequences and a 2N-Point real sequence, Design of FIR Filters, Design of linear phase FIR Filters using window methods and frequency sampling method, Design of IIR Digital Filters from Analog Filters, IIR Filter Design, Frequency Transformations, FIR Filter Structures, IIR Filter Structures, Introduction to TMS320C67xx digital signal processor, Multi-rate Digital Signal Processing, Finite word length effects in DSP systems, IIR digital filters, FFT algorithms.

Expected outcome:

The students will understand

- (i) the principle of digital signal processing and applications.
- (ii) the utilization of DSP to electronics engineering

Text Books:

- Oppenheim A. V., Schafer R. W. and Buck J. R., Discrete Time Signal Processing, 3/e, Prentice Hall, 2007.
- Proakis J. G. and Manolakis D. G., Digital Signal Processing, 4/e, Pearson Education, 2007.

References:

- Chassaing, Rulph., DSP applications using C and the TMS320C6x DSK. Vol. 13. John Wiley & Sons, 2003.
- Ifeachor E.C. and Jervis B. W., Digital Signal Processing: A Practical Approach, 2/e, Pearson Education, 2009.
- Lyons, Richard G., Understanding Digital Signal Processing, 3/e. Pearson Education India, 2004.
- Mitra S. K., Digital Signal Processing: A Computer Based Approach, 4/e McGraw Hill (India), 2014.
- 5. NagoorKani, Digital Signal Processing, 2e, Mc Graw –Hill Education New Delhi, 2013
- Salivahanan, Digital Signal Processing,3e, Mc Graw –Hill Education New Delhi, 2014 (Smart book)
- Singh A., Srinivasan S., Digital Signal Processing: Implementation Using DSP Microprocessors, Cenage Learning, 2012.

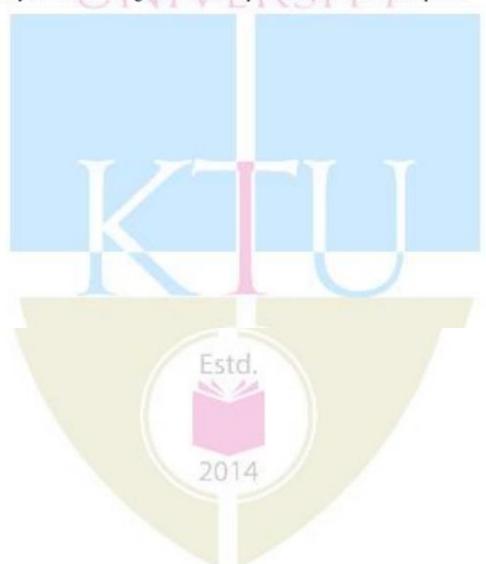
	Course Plan						
Module	Module Course content						
	The Discrete Fourier Transform: DFT as a linear transformation, Relationship of the DFT to other transforms, IDFT	2					
	Properties of DFT and examples Circular convolution	4	1				
I	Linear Filtering methods based on the DFT- linear convolution using circular convolution, overlap save and overlap add methods	3	15				
	Frequency Analysis of Signals using the DFT	2	1				
	Computation of DFT: Radix-2 Decimation in Time and Decimation in Frequency FFT Algorithms	3	1				
II	IDFT computation using Radix-2 FFT Algorithms	2	15				
	Efficient computation of DFT of Two Real Sequences and a 2N-Point Real Sequence	2					
	FIRST INTERNAL EXAM		-				

	Design of FIR Filters- Symmetric and Anti-symmetric FIR Filters	2			
Ш	Design of linear phase FIR Filters using Window methods (rectangular, Hamming and Hanning) and frequency sampling Method	6	15		
	Comparison of Design Methods for Linear Phase FIR Filters	1			
	Design of IIR Digital Filters from Analog Filters (Butterworth)	4			
IV	IIR Filter Design by Impulse Invariance, and Bilinear Transformation	3	15		
	Frequency Transformations in the Analog and Digital Domain	2			
	SECOND INTERNAL EXAM				
	Block diagram and signal flow graph representations of filters	1			
	FIR Filter Structures: (Linear structures), Direct Form,	3			
	Cascade Form and Lattice Structure				
V	IIR Filter Structures: Direct Form, Transposed Form, Cascade Form and Parallel Form	2	20		
	Computational Complexity of Digital filter structures	1			
	Computer architecture for signal processing : Introduction to TMS320C67xx digital signal processor	2			
VI	Multi-rate Digital Signal Processing: Decimation and Interpolation (Time domain and Frequency Domain Interpretation without proof)	3	20		
VI	Finite word length effects in DSP systems: Introduction (analysis not required), fixed-point and floating-point DSP arithmetic, ADC quantization noise	2	20		
	Finite word length offeets in IID digital filters; and	ficient			
	Finite word length effects in IIR digital filters: coefficient quantization errors				
	errors	2			
	END SEMESTER EXAM				

Question Paper Pattern (End Sem Exam)

Maximum Marks: 100 Time : 3 hours

The question paper shall consist of three parts. Part A covers modules I and II, Part B covers modules III and IV, and Part C covers modules V and VI. Each part has three questions uniformly covering the two modules and each question can have maximum four subdivisions. In each part, any two questions are to be answered. Mark patterns are as per the syllabus with 40 % for theory and 60% for logical/numerical problems, derivation and proof.



QUESTION BANK

MODULE I

Q:NO:	QUESTIONS	CO	KL	PAGE NO:
1	Derive the relationship of DFT to Fourier transform	CO1	K3	4
2	Explain the following properties of DFT a) Circular Convolution b) Time Reversal	CO1	K2	8
3	Derive the relationship of DFT to Z-transform.	CO1	K3	12
4	Explain the following properties of DFT a) Complex conjugate property b) Circular Convolution	CO1	K2	16
5	Explain the following properties of DFT a) Linearity b) Complex conjugate property	CO1	K2	23
6	Find the circular convolution of $x1$ (n) = {1, -1, -2,3, -1}, $x2$ (n) = {1,2,3} Using i) Concentric circle method ii) Matrix metho	CO1	K3	30
7	Find the output $y(n)$ of a filter whose impulse response is $h(n)=\{1,1,1\}$ and input $x(n)=\{3,-1,0,1,3,2,0,1,2,1\}$ using i) Overlap-save method ii) Overlap-add method	CO1	K3	31
8	Find the output y(n) of a filter whose impulse response is h(n)={1,1,1} and input x(n)={3,-1,0,1,3,2,0,1,2,1} using i) Overlap-save method ii) Overlap-add method K3/CO1 O	CO1	К3	33
9	The first eight points of 14-point DFT of a real valued sequence are {12, -1+j3, 3+j4, 1-j5, -2+j2, 6+j3, -2-j3, 10,} i) Determine the remaining points ii) Evaluate x[0] without computing the IDFT of X(k)? iii) Evaluate IDFT to obtain the real sequence?	CO1	К3	35
10	Find the remaining samples of the 14-point DFT of the sequence given below $X(K)=\{12,-1+j3,3+j4,1-j5,-2+j2,6+j3,-2-j3,10,\}$	CO1	К3	37
11	Consider the sequence $x(n)=\{1,2,-3,0,1,-1,4,2\}$. Evaluate the following functions without computing the DFT. i) $X(0)$ ii) $X(4)$ iii) $\sum X(K)$ 7 $k=0$ iv) $\sum e$ $-j3\pi k$ 4 7 $k=0$ $X(K)$	CO1	К3	40

	MODULE II								
1	Find the IDFT of the sequence $X(k)=\{10,-2+j2,-2,-2-1\}$	CO2	K5	49					
	j2} using DIT algorithm								
2	Compute 4-point DFT of a sequence $x(n)=\{0,1,2,3\}$ using DIF algorithm	CO2	K5	51					
3	Compute 4-point DFT of a sequence $x(n)=\{0,1,2,3\}$	CO2	K5	52					
	using DIT algorithm.								
4	Compute 4-point DFT of a sequence $x(n)=\{1,0,0,1\}$	CO2	K5	53					
	using DIF algorithm								
5	Compute 4-point DFT of a sequence $x(n)=\{0,1,2,3\}$	CO2	K5	54					
	using DIF algorithm.								
6	Compute 4-point DFT of a sequence $x(n)=\{1,-1,1,-1\}$ using DIT algorithm.	CO2	K5	62					
7	Find the 8 point DFT of a real sequence $x(n)=\{1,2,3,4,4,3,2,1\}$ using radix-2 decimation in time algorithm	CO2	К3	65					
8	Compute the eight point DFT of the sequence $x(n) =$	CO2	К3	66					
9	{ $1 \ 0 \le n \le 7 \ 0 \ otherwise$ } By using DIF algorithms. Compute the 8 point DFT of $x(n) = \{2,1,-1,3,5,2,4,1\}$	CO2	K3	68					
9	using radix-2 decimation in time FFT algorithm.	CO2	KS	08					
10	Find the 8 point DFT of a real sequence	CO2	К3	70					
	$x(n)=\{1,2,2,2,1,0,0,0,0\}$ using radix-2 decimation in								
	frequency algorithm.								
11	Compute the eight point DFT of the sequence $x(n) =$	CO2	К3	72					
	$\{10 \le n \le 70 \text{ otherwise}\}$ By using DIT algorithm								
	MODULE III								
1	Design a low pass filter with passband gain of unity,	CO3	K6	85					
	cutoff frequency of 1000Hz and working at a								
	sampling frequency of 5KHz. The length of the								

	impulse response should be 7. Use a rectangular			
	window technique.			
	Design a linear phase FIR low pass filter with cutoff frequency of 2KHz and sampling rate of 8KHz with a filter length 11 using Hanning window	CO3	K6	87
	Design a FIR filter approximately the ideal frequency response Hd(e j ω) = e $-j\alpha\omega$ for $ \omega \le \pi$ 6 = 0 for π 6 \le $ \omega \le \pi$ Use Hamming window. Determine the filter coefficients for N=13	CO3	K6	89
	Explain the frequency sampling method of FIR filter design	CO3	K2	90
	Give equations for N point Hamming and Hanning window functions. Compare them in terms of main lobe width and side lobe level	CO3	K2	91
	State the condition for the impulse response of FIR filter to satisfy for constant group and phase delay and for only constant group delay.	CO3	K2	94
	Differentiate between FIR filters and IIR filters	CO3	K2	95
1	Illustrate the design of IIR filters from Analog Filters	C04	К3	99
1	Illustrate the design of IIR filters from Analog Filters.	CO4	К3	99
	Design an analog butterworth filter that has a -2dB passband attenuation at a frequency of 20rad/sec and atleast -10dB stopband attenuation at 30rad/sec.	CO4	K3	102
	For the given specifications design an analog Butterworth filter. $0.9 \le H(j\Omega) \le 1$ for $0 \le \Omega \le 0.2\pi$. $ H(j\Omega) \le 0.2$ for $0.4\pi \le \Omega \le \pi$.	CO4	К3	103
4	Design an analog butterworth filter that has a -2dB passband attenuation at a frequency of 20rad/sec and atleast -10dB stopband attenuation at 30rad/sec.	CO4	К3	105
5	Design an analog butterworth filter that has a -2dB passband attenuation at a frequency of 20rad/sec and atleast -10dB stopband attenuation at 30rad/sec.	CO4	К3	107
6	Illustrate the design of IIR filters from Analog Filters.	CO4	К3	110
U		004	TZC	
7	Design a digital butterworth filter satisfying the constraints $0.707 \le H(e \ j\omega) \le 1$ for $0 \le \omega \le \pi \ 2$ H(e $j\omega) \le 0.2$ for $3\pi \ 4 \le \omega \le \pi$ With $T=1$ sec. Use Bilinear transform.	CO4	K6	111

	order butterworth digital filter using impulse			
	invariance technique. $H(s) = 1 \ s \ 2 + \sqrt{2} \ s + 1$			
9	Apply bilinear transformation to $H(s)=2$ ($s+1$)($s+2$) with $T=1$ sec and find $H(Z)$	CO4	K3	114
10	Design a digital butterworth filter satisfying the constraints $0.707 \le H(e \ j\omega) \le 1$ for $0 \le \omega \le \pi \ 2$ H(e $j\omega) \le 0.2$ for $3\pi \ 4 \le \omega \le \pi$ With $T=1$ sec. Use Bilinear transform.	CO4	K6	116
	MODULE V			
1	Define a signal flow graph. Draw the signal flow graph of first order digital filter.	CO5	K2	126
2	Sketch a cascade realization of FIR filter structure with complex zeros.	CO5	К3	135
3	Realize the transposed form structure for the system $Y(n) = -0.1y(n-1) +0.2y(n-2) +3x(n) +3.6x(n-1) +0.6x(n-2)$	CO5	K3	138
4	Realize the system with difference equation $y(n)=34$ $y(n-1)-18$ $y(n-2)+x(n)+13$ $x(n-1)$ in cascade form.	CO5	К3	141
5	Draw the direct form I and direct form II structures for the difference equation $y(n) = x(n) + 0.5x(n-1) + 3y(n-1)-2y(n-2)$	CO5	К3	143
6	Draw the cascade form structure for a discrete time sequence described H(Z)= $1+12z-11-34z-1+18z-2$	CO5	К3	146
7	Realize the system function using minimum number of multipliers $H(Z) = (1+z-1)(1+0.5z-1+0.5z-2+z-3)$	CO5	К3	147
8	Obtain the parallel form structure for the system given by the difference equation $y(n) = -0.1y(n-1) +0.72y(n-2) +0.7x(n) -0.252x(n-2)$	CO5	К3	149
9	Draw the block diagram of TMS320C67xx and briefly explain function of all blocks.	CO5	К3	151
	MODULE VI			
1	Draw the block diagram of ADC quantization noise and explain in detail.	CO6	К3	153
2	Explain the effects of coefficient quantization in FIR and IIR filters.	CO6	K2	154

3	Derive the variance of quantization noise in ADC.	CO6	К3	156
	Assume step size is Δ .			
	Let $x(n) = 0.5 \square u(n)$. Obtain the signals for	CO6	K2	157
4	decimation by 3, interpolation by 3.			
5	Write notes on finite word length effects in DSP	CO6	K2	158
	systems.			
6	Let a signal $x(n) = 0.5 \square u(n)$ is decimated by 2.	CO6	K2	162
	What happens to its spectrum?			
7	Derive Decimation In Time (DIT) FFT algorithm for	CO6	K5	170
	8 point DFT and draw the signal flow graph.			
8	Explain the effect in the spectrum of a signal $x(n)$	CO6	K3	171
	when it is (i) Decimated by a factor 3 (ii) Interpolated			
	by a factor 2 (5)			

APPENDIX 1

CONTENT BEYOND THE SYLLABUS

S:NO;	TOPIC	PAGE NO:
1	Array Signal Processing	180

Stelle MODULE - 1

Discrete Fourier Transform. (DFT)

DFT
$$\rightarrow x(k) = \sum_{n=0}^{N-1} x(n) e^{-j\frac{2\pi i n k}{N}}$$

IDFT
$$\rightarrow \alpha(n) = \frac{1}{N} \sum_{k=0}^{N-1} x(k) e^{j2\pi i n k}$$

$$zoln$$
: $N = 4$.

$$X(K) = \sum_{n=0}^{3} \alpha(n) e^{-j\frac{2\pi nK}{4}}$$

Since
$$N=4$$
, we have to find $x(0), x(1), x(2), x(3)$.

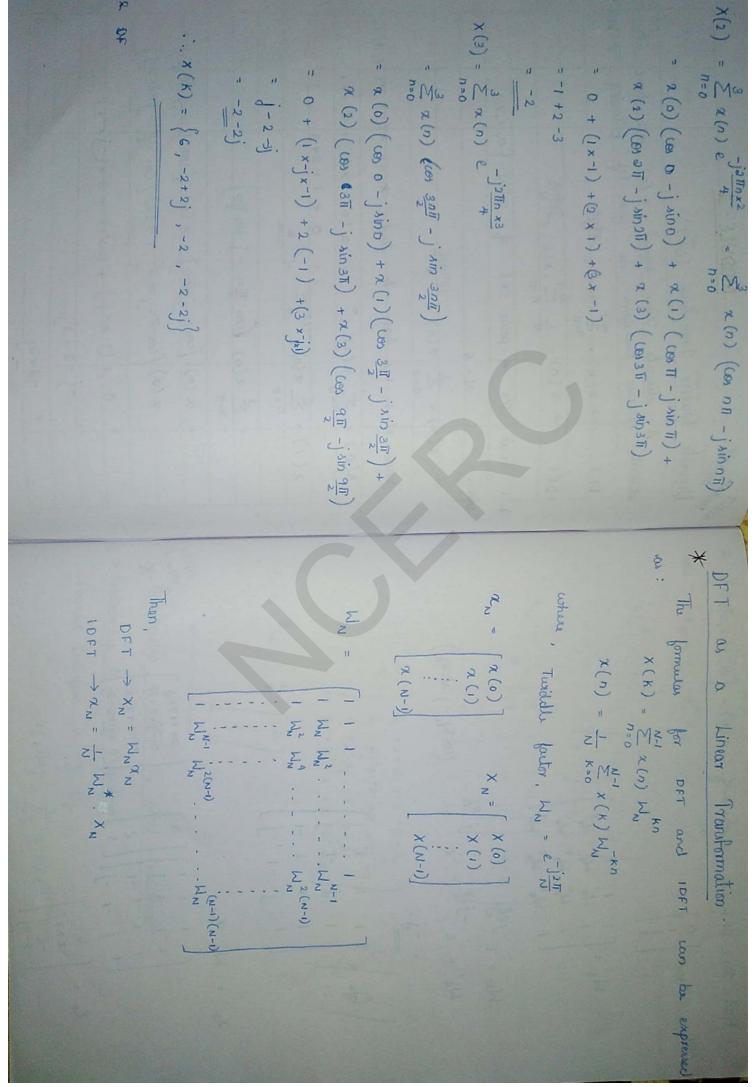
$$\chi(0) = \sum_{n=0}^{3} \chi(n) e^{0} = \chi(0) + \chi(1) + \chi(2) + \chi(3).$$

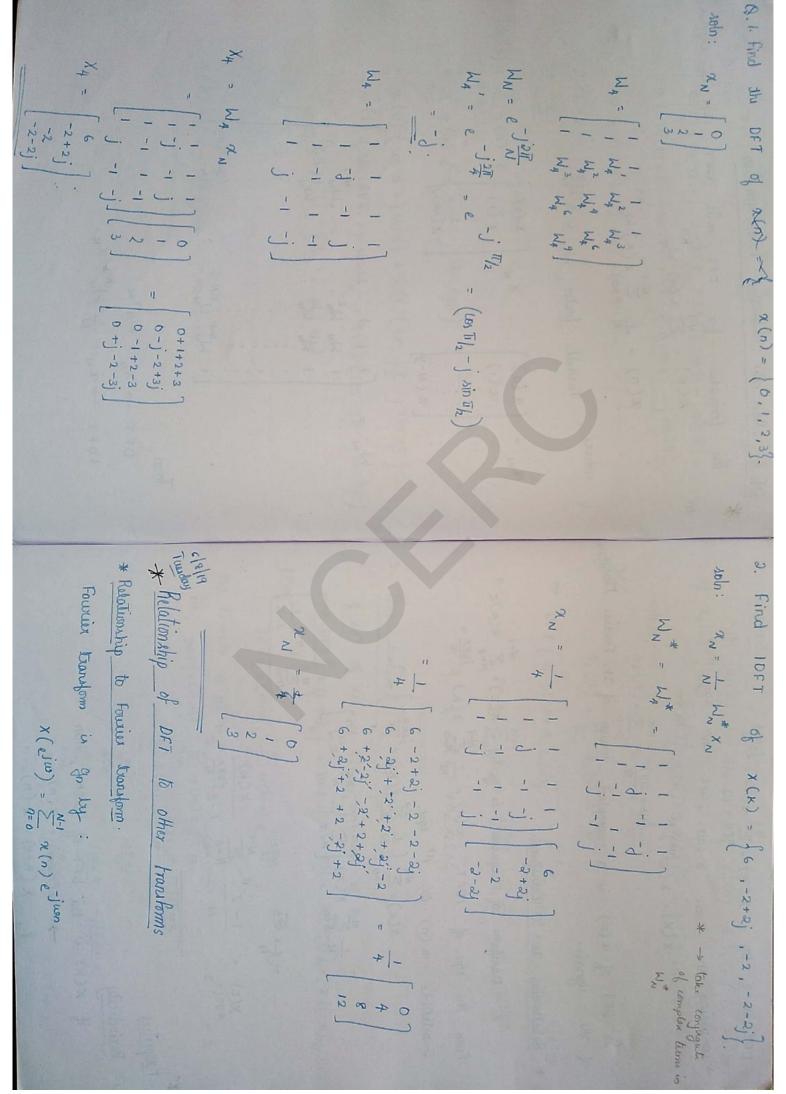
$$x(1) = \frac{3}{2} \alpha(n) \cdot e^{-j2\pi n x i} = 0 + 1 + 2 + 3$$

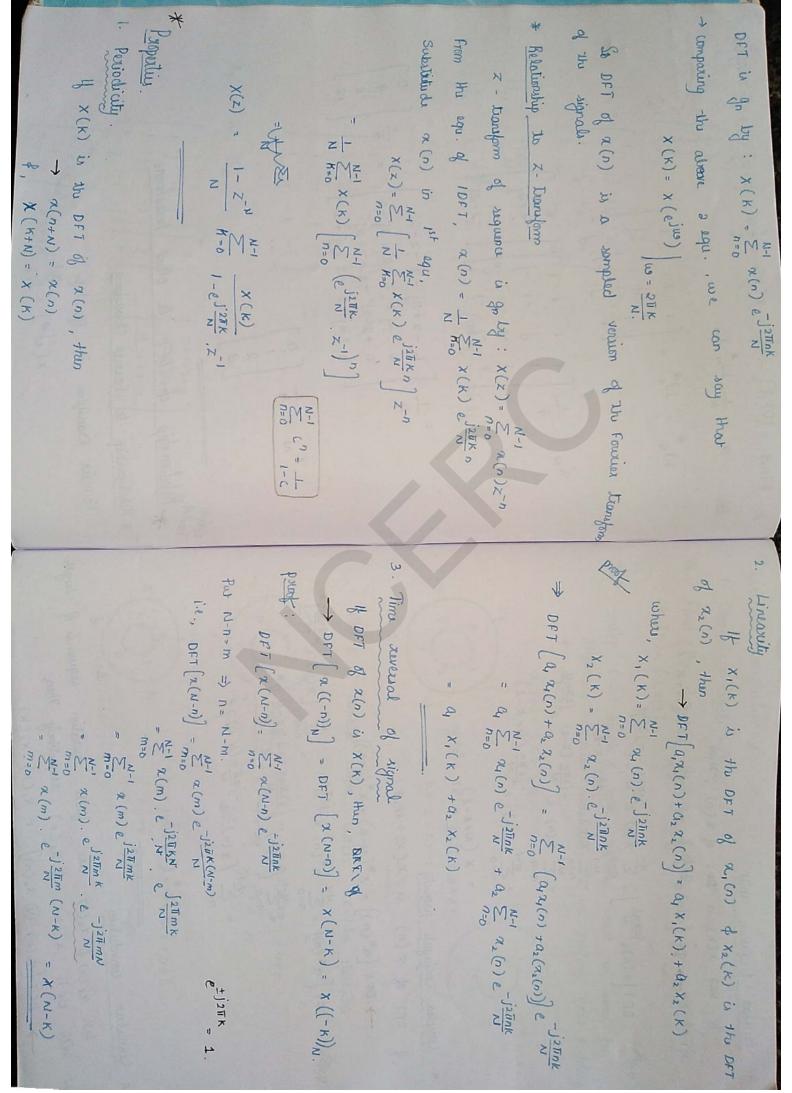
$$= \sum_{n=0}^{3} \alpha(n) \left(\cos \frac{\pi}{2} n - j \sin \frac{\pi}{2} \right)$$

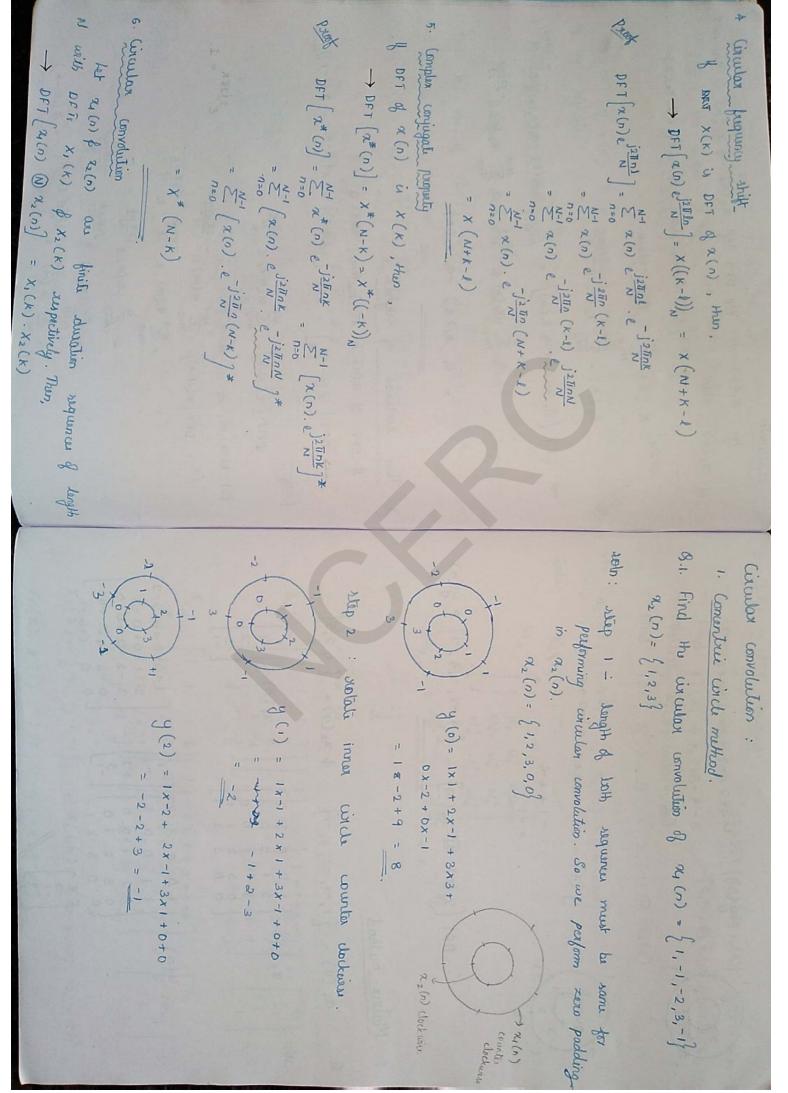
$$= \alpha(0) \cdot \left[\cos 0 - j\sin 0\right] + \alpha(1) \cdot \left[\cos \frac{\pi}{2} - j\sin \frac{\pi}{2}\right] + \alpha(3) \left[\cos \frac{\pi}{2} - j\sin \frac{\pi}{2}\right] + \alpha(3) \left[\cos \frac{3\pi}{2} - j\sin \frac{\pi}{2}\right]$$

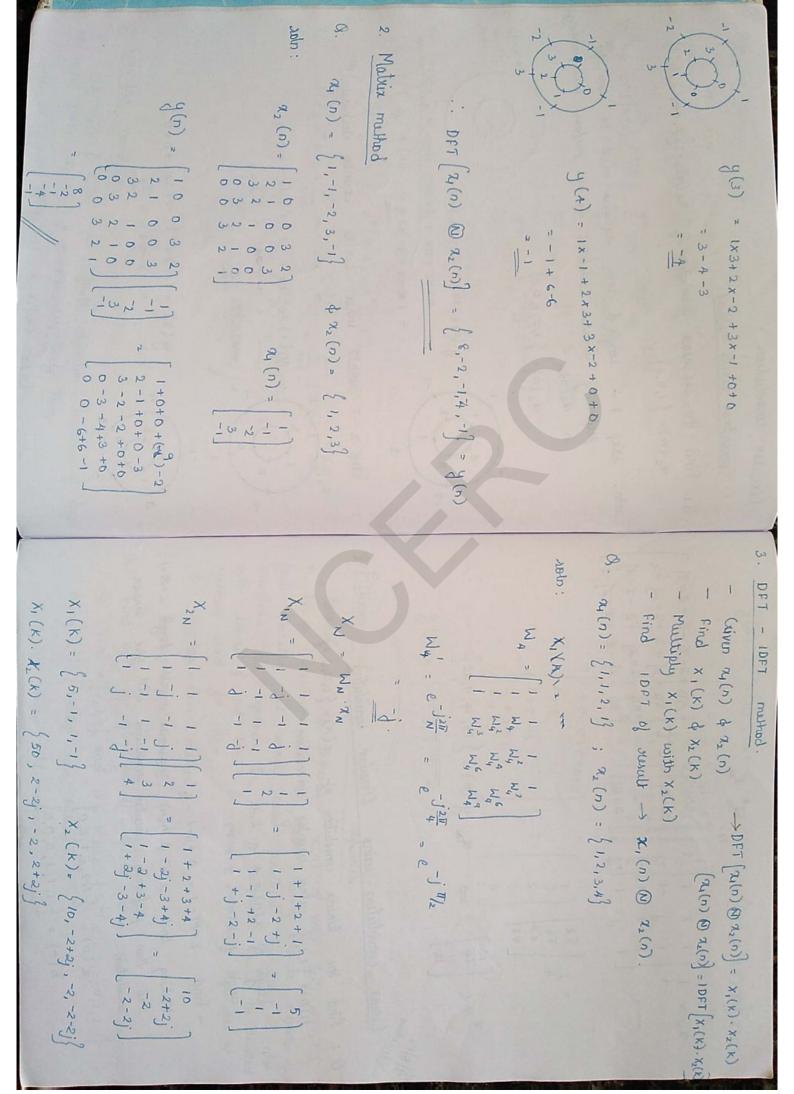
$$= 0 + (1 \times -j) + (2 \times 1) + 3 \times (-j \times -1)$$

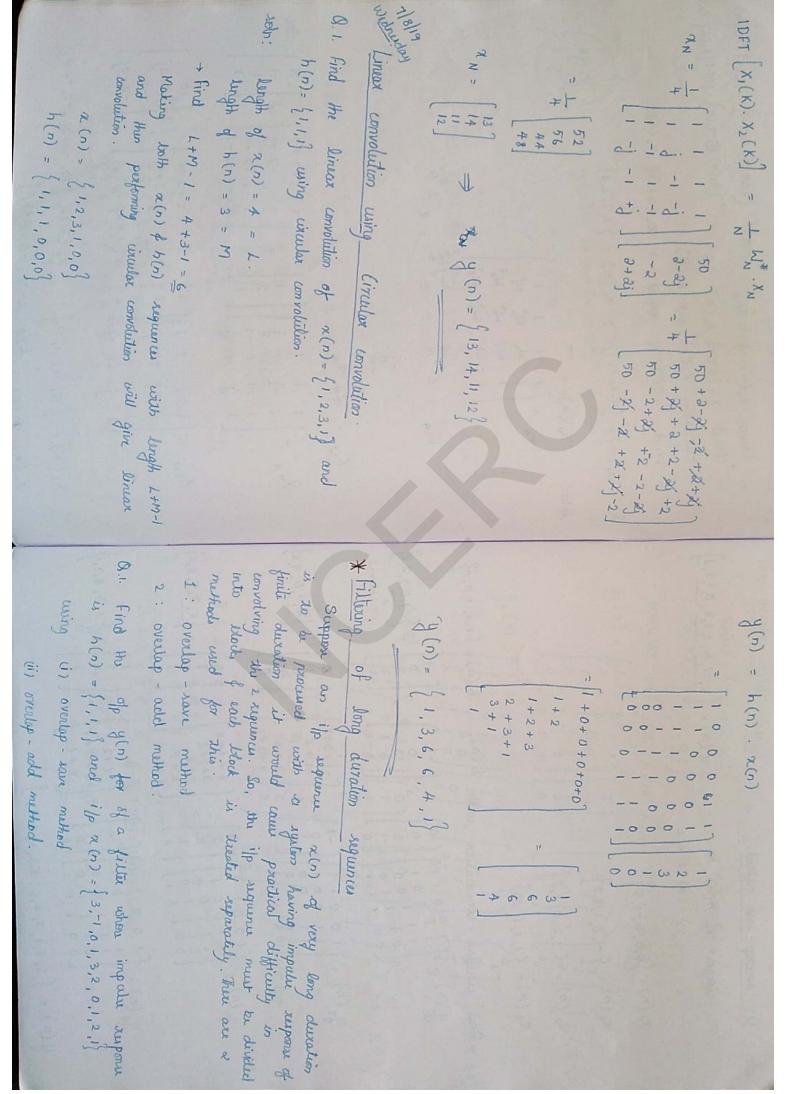


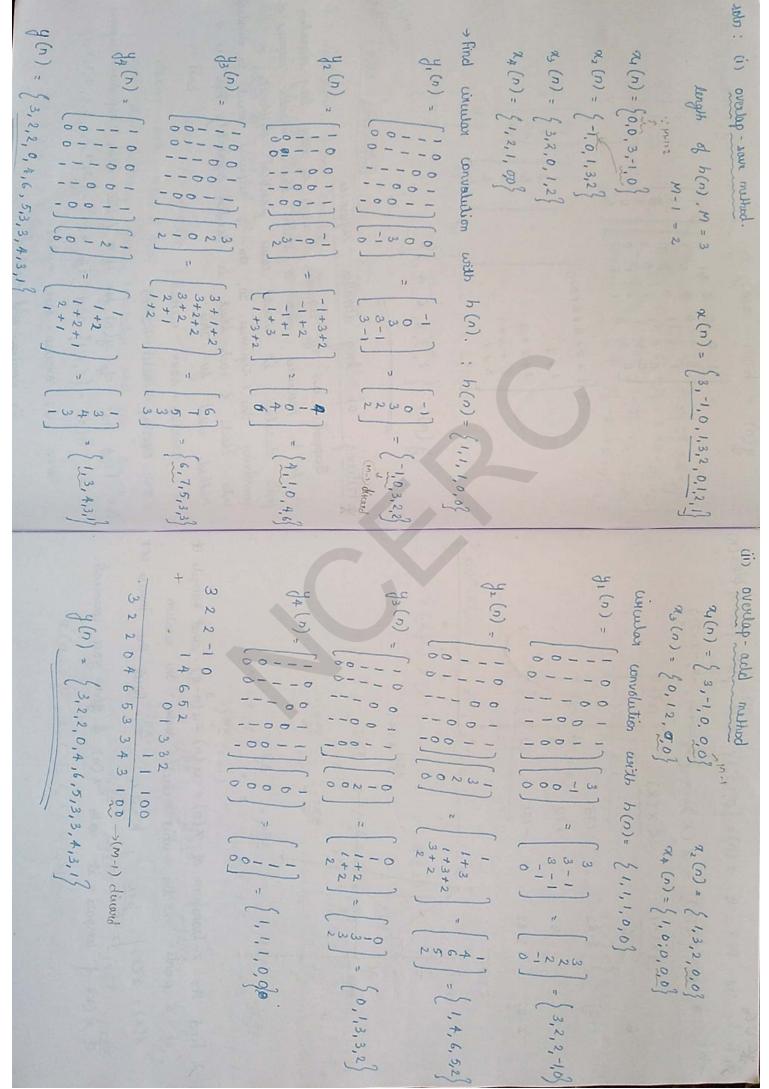


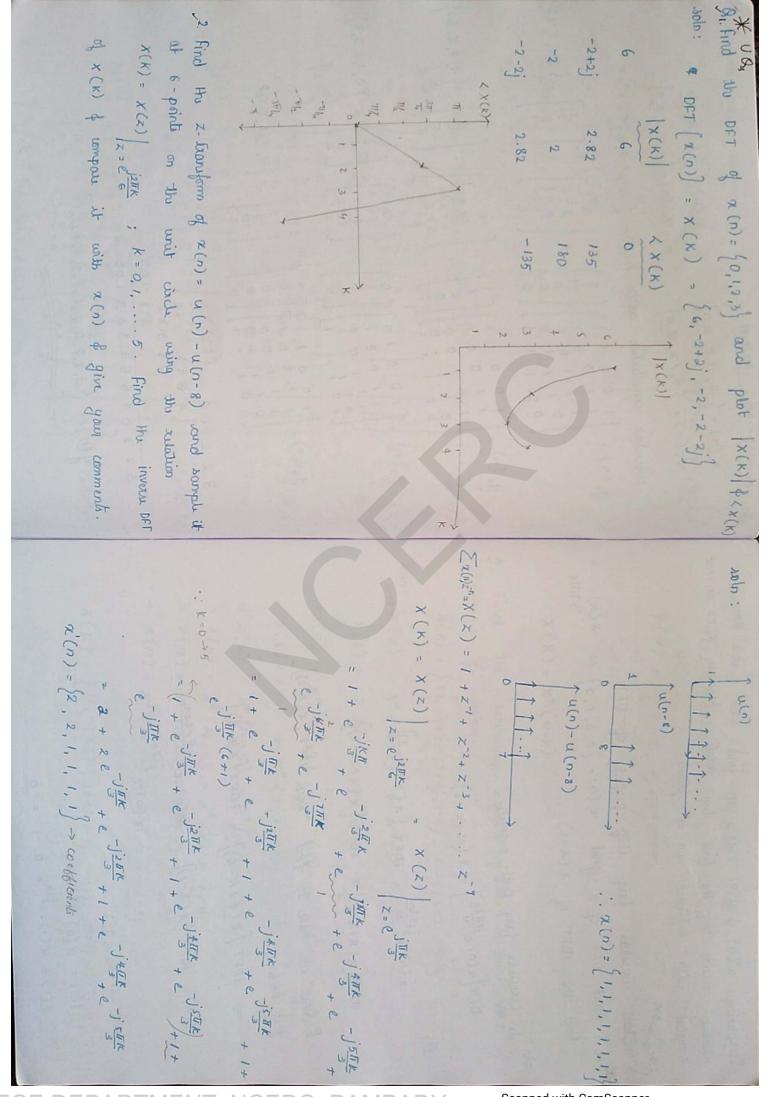






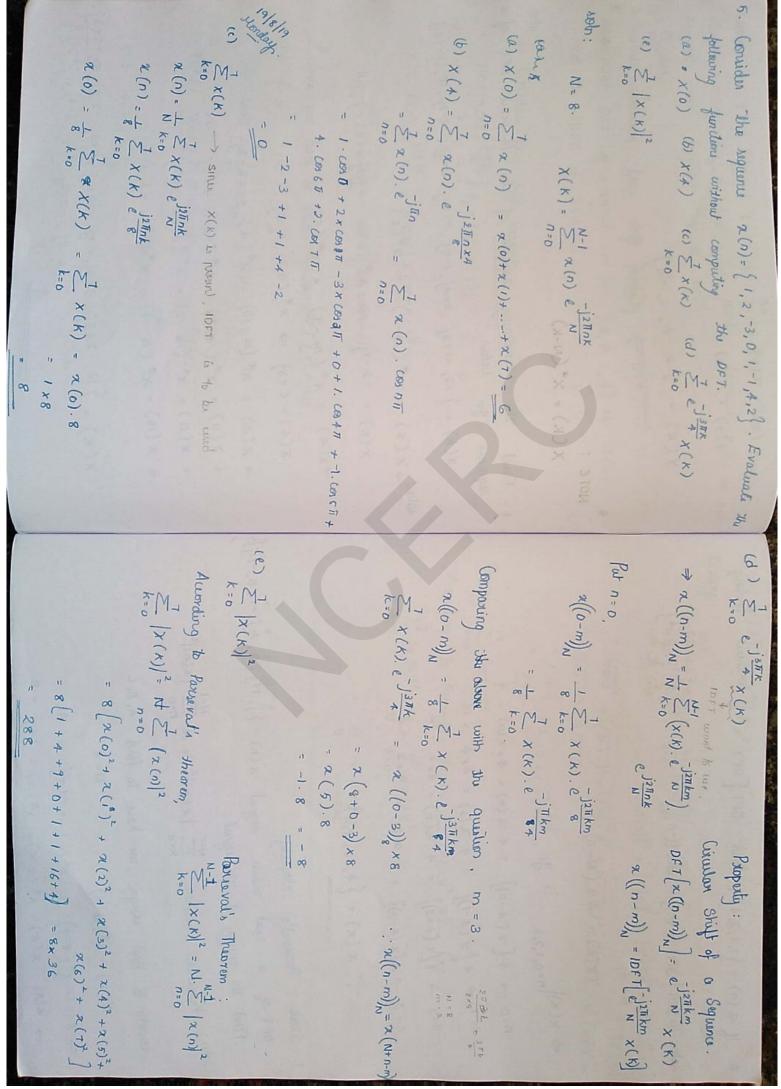


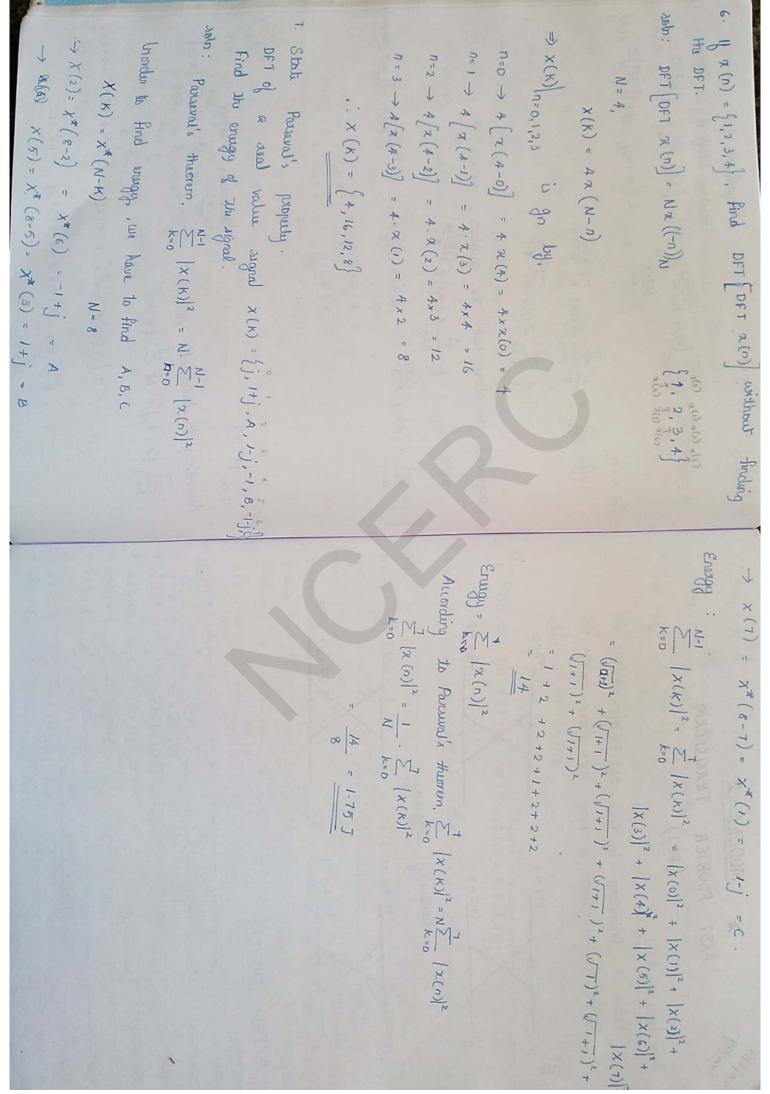


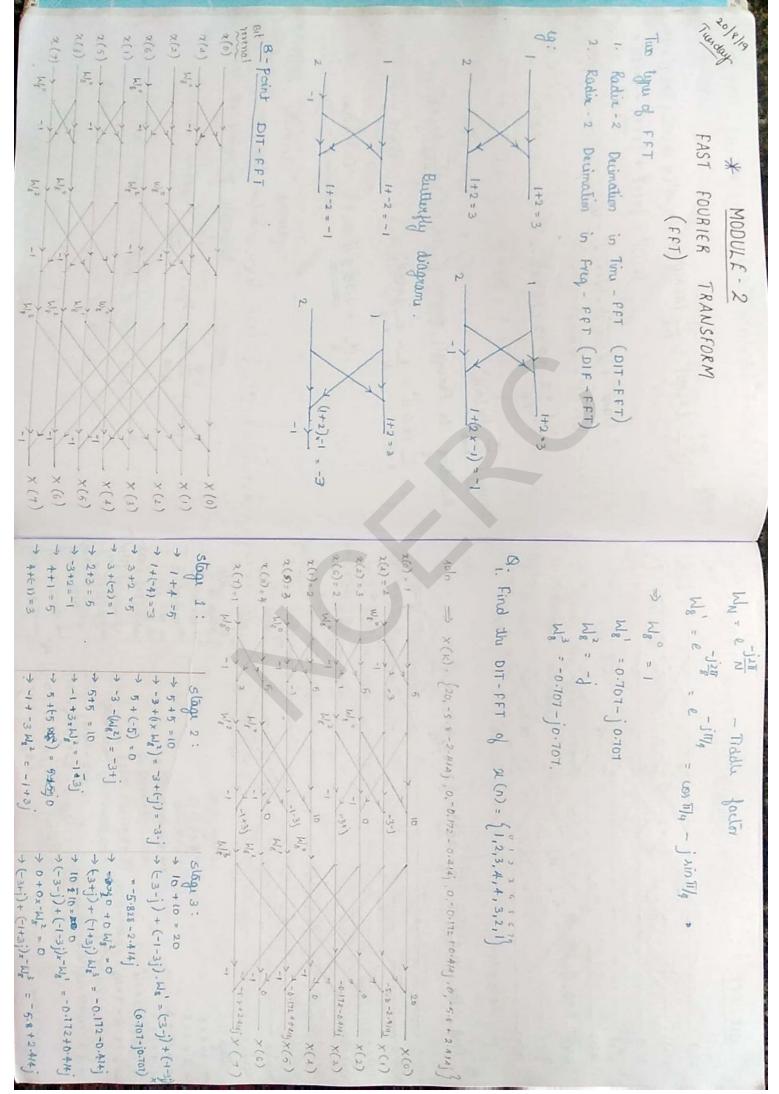


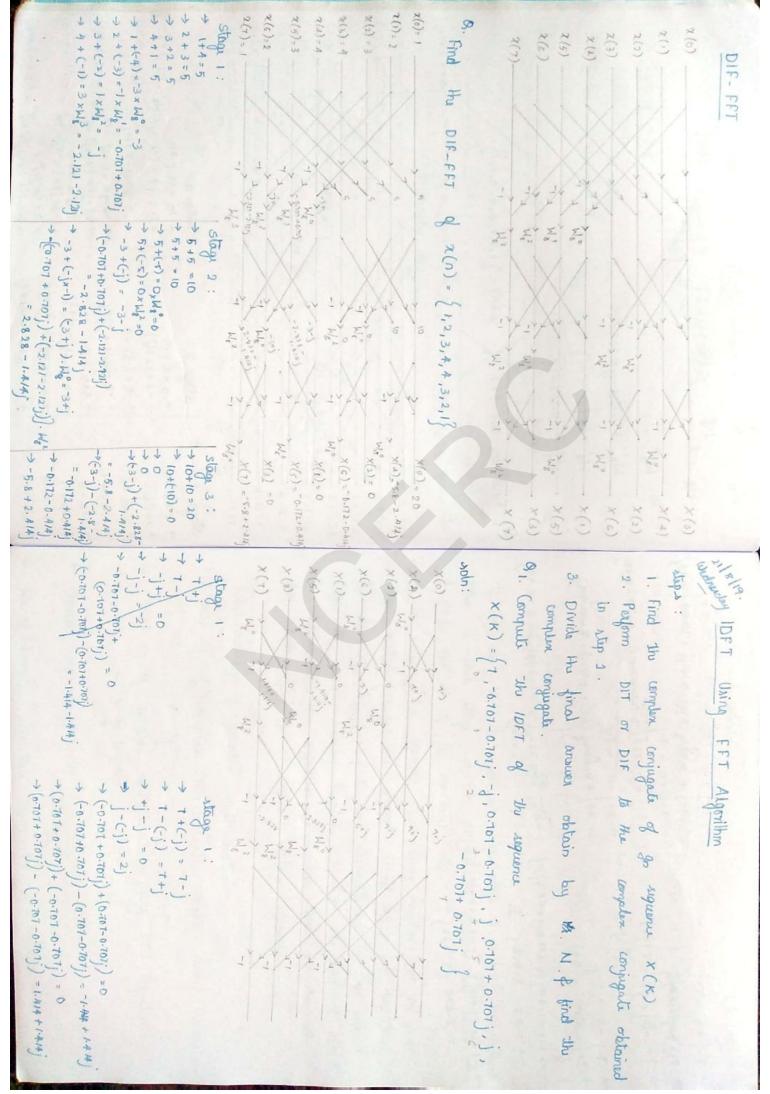
ECE DEPARTMENT, NCERC, PAMPADY

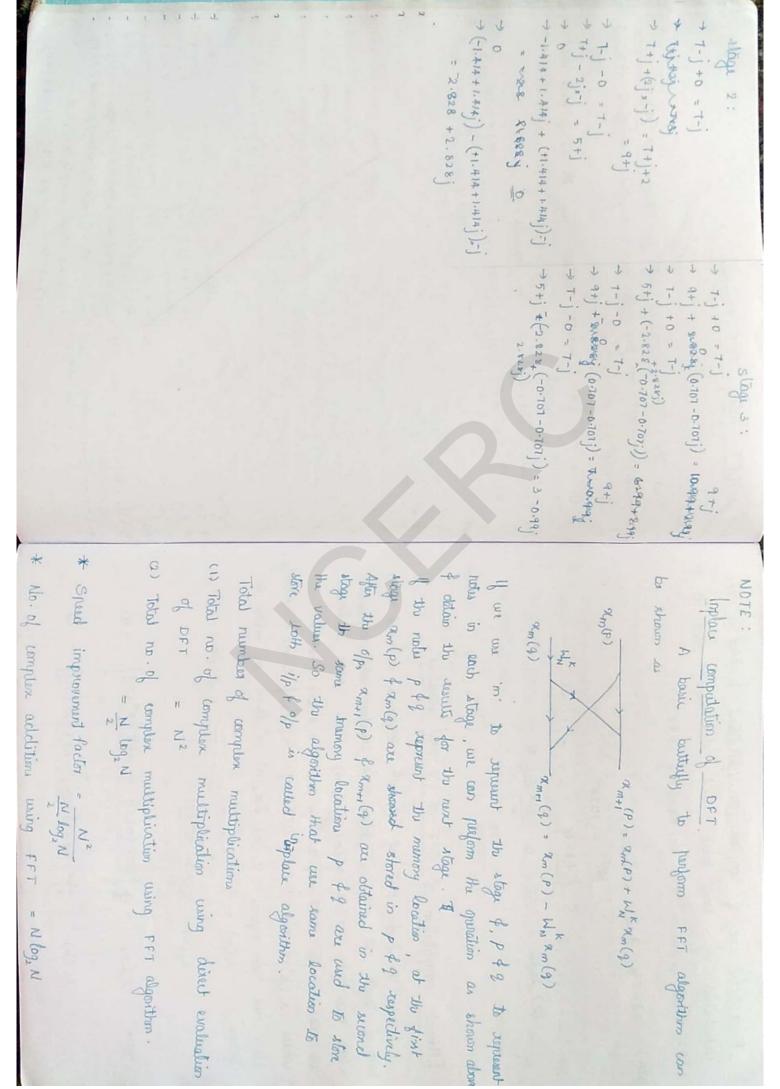
* (ii) A - point DET of a signal & (n) = {a, b, c, d} is find the IDET of x (K-2). note: Circular freq shift property Comparing $\alpha'(n) \neq \alpha(n)$ we can find that time domain aliasing occurs in the first two points because $\kappa(z)$ is sampled with sufficient no of points. put n=0,1,2,3. & Since we have to find xo(x 1DFT [x(x-2)] Y(K) = 10FT [x(K-2)] = a(n). e j2 1/2 (x 6xn) → IDFT [x(4+K-6)] = IDFT[x(K-2)] $DFT\left(\mathcal{R}(n) e^{\frac{j2\pi I_{i}}{N}}\right) = X\left(N+K-I\right)$ 4(1) = 2(1). ejst = b. -1 = -b IDFT[X(K+N-1)] = IDFT[X(4+K-1)]4(0) = x(0).e0 = Z(n) e Jath = IDFT (X(N+K-1)) N(n).e jatin become x(z) is not X(K) 4. Find the sumaining samples of the 14-point DFT of a $(9)_{*}X = (8-41)_{*}X = (8)_{X} \leftarrow 0$ NOTE : $(X(K) = \{12, -7+3j, 3+4j, 1-5j, -2+2j, 6+3j, -2-3j\}$ >x(9) = x*(14-9) = x*(5) $\rightarrow x(10) = x^*(14-10) = x^*(4) = -2-2$ $x(5) = 6+3j \Rightarrow x^*(5) = 6-3j$ $X(K) = \begin{cases} 12, -1+3j, 3+4j, 1-5j, -2+2j, 6+3j, -2-3j, 10, \dots \end{cases}$ X(K) = X*(N-K) Y(K) = {0,-6, c,-d} $X(12) = X^*(14-12) = X^*(2) = 3-4$ $X(13) = X^*(14-13) = X^*(1) = -1-3j$ $X(6) = -2-3j \implies X*(6) = -2+3j$ $X(u) = X^*(14-11) = X^*(3) = 1+5j$ Y (2) = x(2). e J 6/1 $Y(3) = \Re(2) \cdot e^{3} = C \cdot 1 = C$ 6-3, -2-2, 1+5, 3-4, -1-3, 2











both of longth 11, let us define a complex value sequence su(n) such that $\alpha(n) = \alpha_1(n) + j \alpha_2(n)$. Since per is linear we can write DFT of $\alpha(n) = \chi(K) = \chi_1(K) + j \chi_2(K)$ S. Find the no- of complex multiplication where X, (K) \$ x2(K) are DFT, of 2,(0) \$ x2(0) regularly COURTIN Now we can express of a (n) fixe(n) in terms of a (n) or Efficient computation of DFT of 2 real sequences (0) client evaluation (b) Baix -2 FFT calculation of 1024 paint DFT using broades to find DFT of 2 such suguences 24(n) & va(n) (b) Radia -2 FFT = N3 log N (a) by direct evaluation $x_{2}(K) = \frac{1}{2j} \left[DFT \left[x(n) \right] - DFT \left[x^{*}(n) \right] \right] - 2$ X,(K) = \$ DFT [x(n)] + DFT [x*(n)] 24(11) = 2(11) + 2*(11) $x_{2}(0) = x_{2}(0) - x^{*}(0)$ 1048576 Nº = 10242 * 5120 involved in the

Using mation muthod, DFT, XN = WN 24 DFT [x(n)] = x(k) \$ DFT [x*(n)] = x*(N-K) Given g(n) = {1,0,1,0} & .h(n) = {1,2,2,1} . Find Hu 4-point DET. 4-point Dri, of Hore the 2 reguences ceeing a ringle O & O benomina 2(n) = { 1+j , 2j , 1+2j , j} 9(1) = {1,0,1,0} h(n) = {1,2,2,1} $X_2(K) = \frac{1}{2j} \left[X(K) - X^*(N-K) \right]$ $X_{1}(K) = \frac{1}{2} \left[X(K) + X^{*}(N-K) \right]$ $\begin{bmatrix}
 | +j + 2 -1 - 2j - 1 \\
 | +j - 2j + 2j - j
 \end{bmatrix}$ $\begin{bmatrix}
 | +j - 2j + 1 \\
 | +j - 2j + 1
 \end{bmatrix}$ 1+j+2j+1+2j+1 ¥ " 1-1-2 + i - j

 $\begin{array}{lll}
X^{*}(A-1) &= X^{*}(3) &= -1+j \\
X^{*}(A-2) &= X^{*}(1) &= 1+j \\
X^{*}(A-3) &= X^{*}(1) &= 1+j \\
X^{*}(A-2) &= X^{*}(1+j) \\$

the sequence. Real sequence.

X* (N-K) = X* (4-K)

X*(K) = {2+6j, 1-j, 2, -1-j}

Put K = 0, 1,2,3

x*(4-0) = x*(A) = x*(0) = 2-6

Suppose that g(n) is a real value requere of 2N points. Now we define $\pi_{+}(n) = g(2n)$; $\pi_{2}(n) = g(2n+1)$. Thus we have subdivided -the 2N point sequences. Let $\pi_{-}(n)$ be complex value sequences: $\pi_{-}(n) = \pi_{+}(n) + [\pi_{2}(n)]$.

From the stream of previous rection:

 $x_{1}(K) = \frac{1}{2} \left[x(K) + x^{*}(N-K) \right]$

x2 (K) = 1 [x(K)-x*(N-K]

We express the 2N-point DET in terms of two N-point

DFT X, (K) & 15(K). For that we we calculation

in DIT adaptithm.

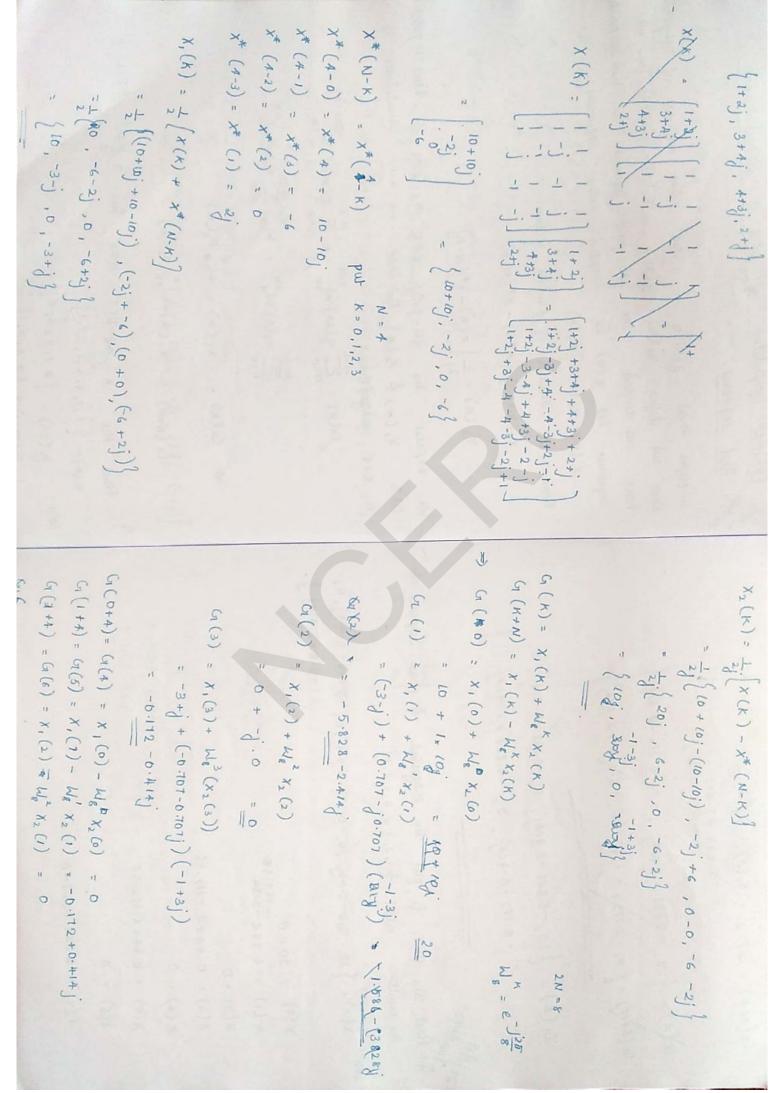
Gi(k) = $\sum_{n=0}^{N-1} q^{(2n)} \bowtie_{2N}^{2NK} + \sum_{n=0}^{N-1} q^{(2n+1)K} \bowtie_{2N}^{(2n+1)K}$

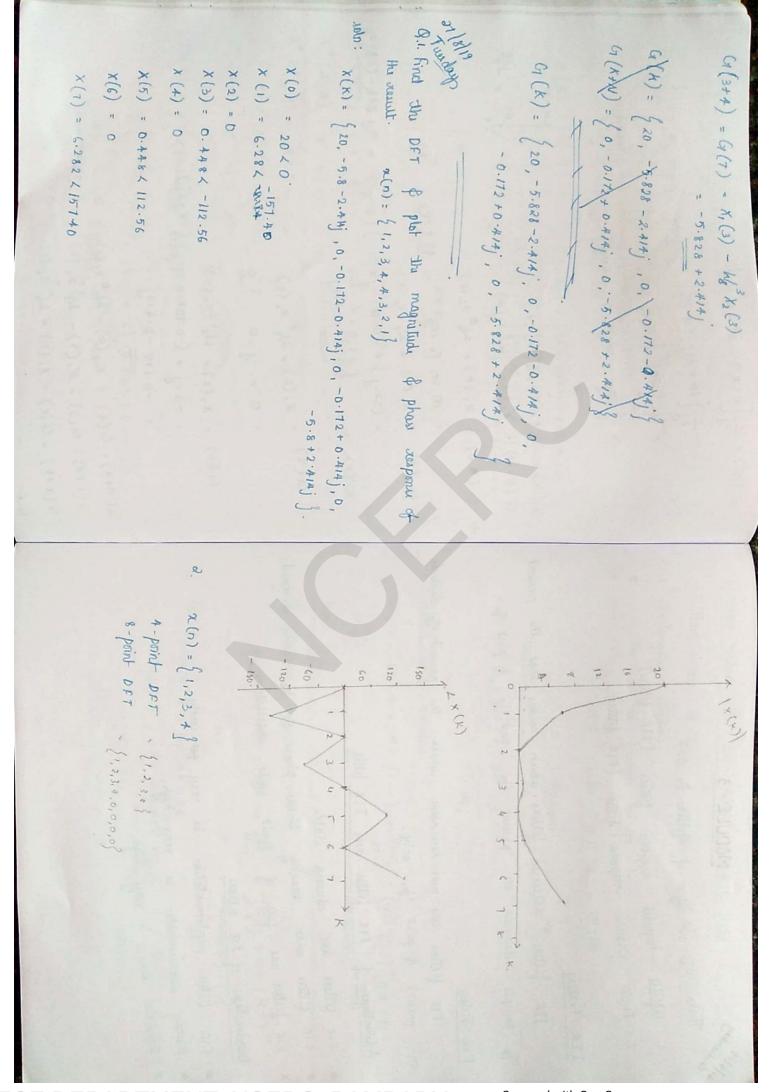
 $\sum_{n=0}^{N-1} g_{1}(2n) \bowtie_{N} + \bigotimes_{n=0}^{N} g_{2n+1}) \bowtie_{2N}$ $= \sum_{n=0}^{N-1} g_{1}(n) \bowtie_{N}^{n} + \bigotimes_{N} \bigotimes_{n=0}^{N-1} g_{2}(n) \bowtie_{N}^{n} + \bigotimes_{n=0}^{N} g_{2n}(n) \otimes_{N}^{n} \otimes_{N}^{N} \otimes_{N}^{N} + \bigotimes_{n=0}^{N} g_{2n}(n) \otimes_{N}^{N} \otimes_$

G(K) - X1(K) + W21 X2(K)

(1 (K+N) = X, (K)-W/2N X2(K)

8. Find He 8-point DFT using \$100 4-point DFT wing \$100 4-point DFT with a solution $a(n) = \{1, 2, 3, 4, 4, 3, 2, 1\}$ with: $a(2n) = \{0, 1, 3, 4, 0, 3\}$





FIR filters are always stable.

FIR filters with exactly linear phase can be easily designed. of sample defunds on purery ip, past ip & past of. Disadvantages of FIR filliery IIR FILLOW FIR filter implementation is very the confly. Advantage of FIR filter over IIR filler Memory suguirements is very high. Execution time is very high. 1. Infinite Imputes suspones filler (11k filters) There are a find of filter in DSP. Filler present & post 1/p, only. IIR fitting are remaine fitting, which means that the pount FIR filling any non-summerine, where the present of depute Finite impulu suspone filter (FIR filter). MODULE - 3

Mindow method for the design of FIR fills.

There are 3 types of windows, that we use.

1. Rectangulax window function is an by, $M_R(n) = 1$; for -(N-1) $\leq n \leq (N-1)$ sin use.

2. Rained asin window.

 $|| \mathcal{L}_{X}(n) || = || x + (1 - \kappa) \cos \frac{2\pi n}{N-1} ; || n || \frac{1}{2} || \le n \le (\frac{N-1}{2}) || \le (\frac{N-1$

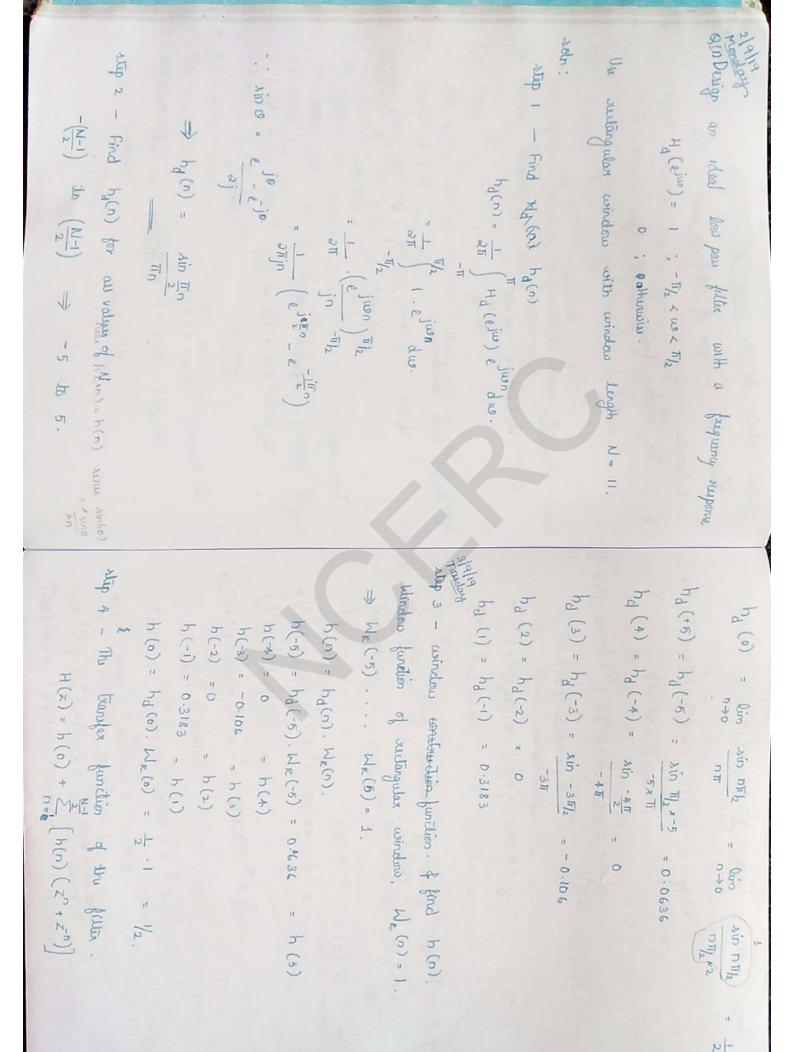
Hamming -> put a = 0.54

WHM (n) = 0.54 + 0.46

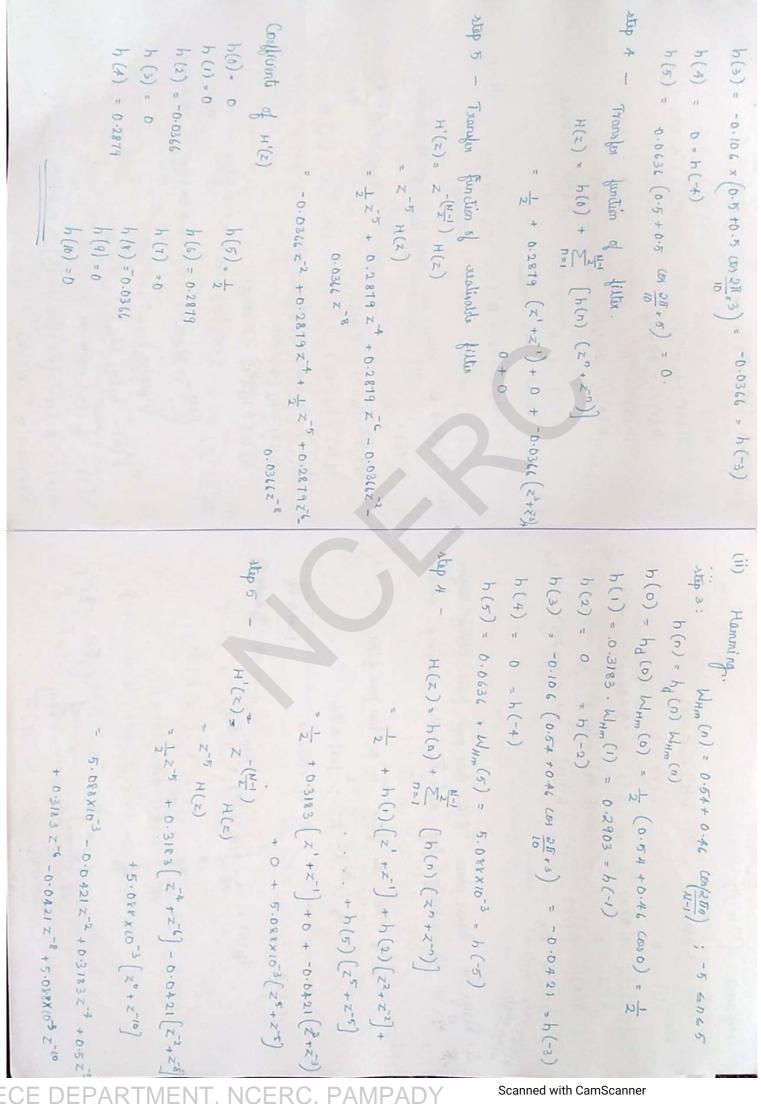
(M-1)

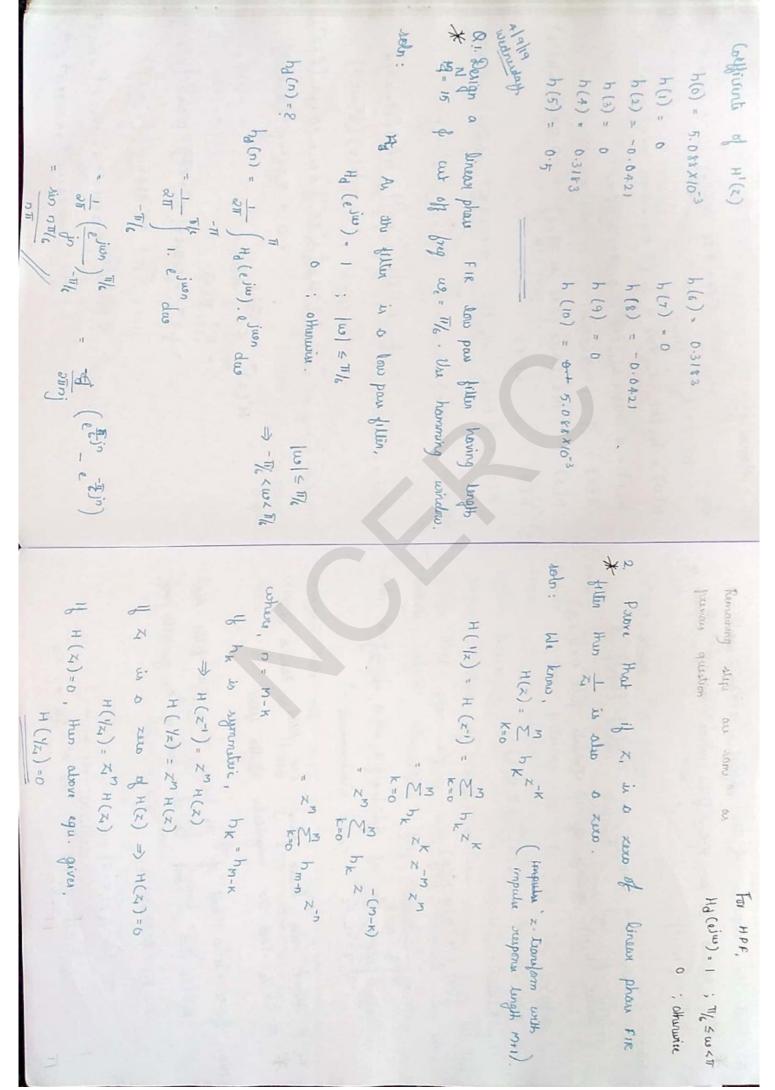
; - (N-1) = n = (N-1)

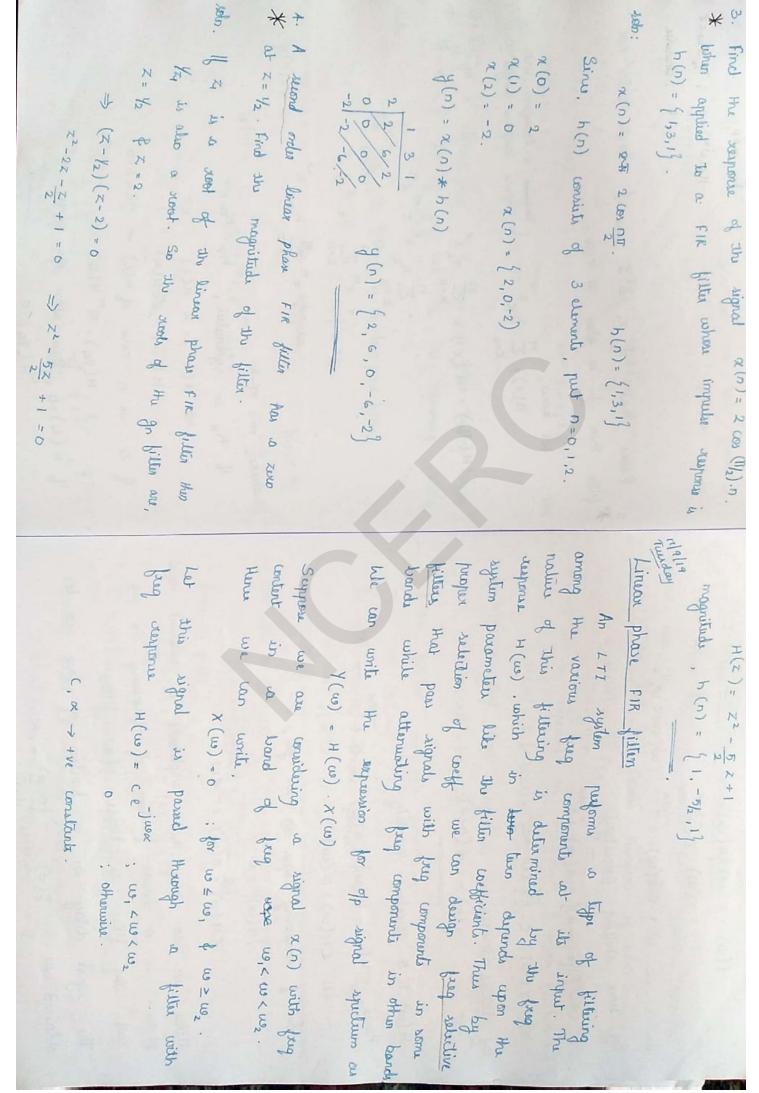
, otherwore.



step 5 - Transfer function of studioath filler. $H'(z) = z^{-5} \cdot H(z)$ H(z) - h(0) + 5 [h(n) (z0+ z0)] H'(z) = Z-(NZ) H(z). = x-5 (1 +0.3183 (x+z-1) -0.106 (z3+z-3)+ 1 z-5 + 0.3183z-4 + 0.3183z-6 - 0.106z-2 -0.9636 - 0.1062-2 + 0.3183 2-4 + 1 2-5 + (\frac{1}{2}z^{-5} + 0.3183 (\frac{1}{z} + \frac{1}{z}^{-6}) - 0.106 (\frac{1}{z}^{-2} + \frac{1}{z}^{-8}) + \$ h(0) + h(1)(z1+z1) + h(2)(z2+z-2)+ 1 + 0.3183 (z'+z-1) + 0.106 (z3+z-3) + + 0.3183 (x+1+z-1)+ 0 + (-0.106 (z3+z-3) 0.1062 8 + 0.06362 10 + 0.636 0.0636 · · · + h(5)(z5+z-5) 0.31832-4-0.10628 +0.06362 + 0 + 0.0636 (z5+z5) 0.836 (z -10 zo) 0.0636 (z5+z-5) 0.1636 (z5+z-5) John: ho (n) is some as Coefficients of the realized h(0) = 1. (0.5+0.5 (0) = 2 h(1) = 0.3183 x (0.5+0.5 (b) 211) = 0.2879 = h(-1) h(2) = 0 = h(-2) hd (0) = 1 hd (2) = hd (-2) = 0 hd (1) = hd (-1) = 0.3183 hd (3) = hd (-3) = -0.106 hd (4) = hd (-4) = 0 h(n) = hd(n) Idmn(n) hd (5) = hd (-5) = 0.0636 Hur , Who (n) = 0.5 + 0.5 (0) 200 h (4) = 0.3183 h(2) = -0.106 Round comme window (Harring) Hd (esu) = 01; - 1/2 < w < 1/2 = 0.0636 i Otherwise that of pruvious question. filler avec h (5) = 0.5 h(6) = 0-3183 h(T) = 0 h (10) = 0.0636 4 (8) = 76.106 bd (n) = 310 8 110 Since cas is ever for (n) (m) = (n-) (a) > WHA (n) - WHA (-n)

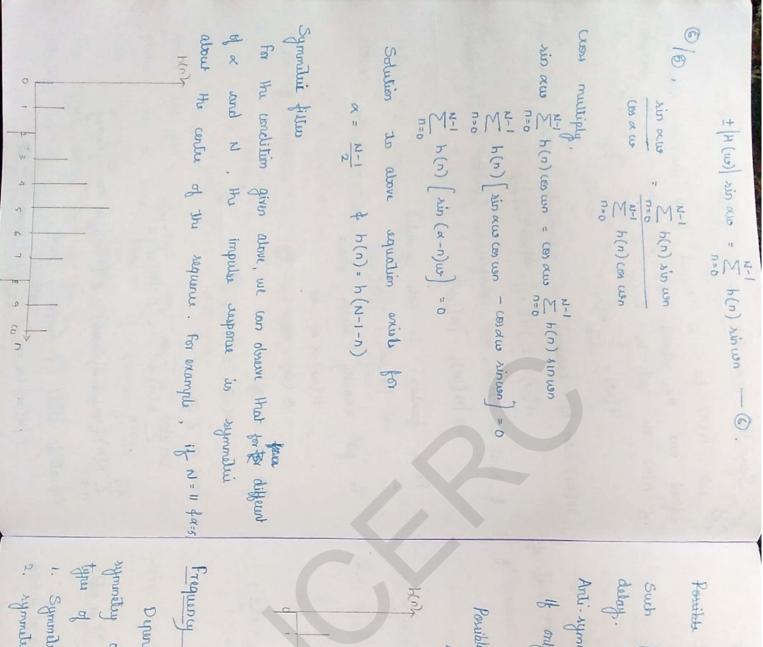


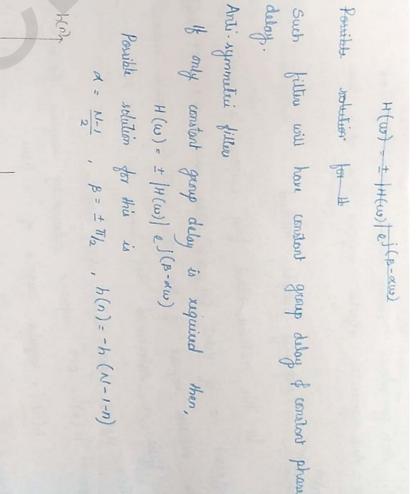




By taking inverse, By time shifting prespectly, Hurse we can say that amplitude is unatant and phase is a linear function of frequency. So we call the filler as linear phase filler. The signal delay as a function of foug can be H (w) is a complex quarterly. Hume, H(w)= |H(w)|. < H(w) ⇒ Y (w) = C. FT 2(n-x) 80 (of [2 (n-a)] = x (w) e jwa & comparing equ. O we get. (m) 0: (m) H> tul Y(w) = x(w). H(w) $y(n) = Cx(n-\alpha)$ /H(w) = C ×H(ω) = 0(ω) = - «ω = x(w). (e) wx T(w) = -do(w) = x cx(w). ¿-jwx = C.e jua in year, en ;

defined over the interval 0 = n = n-1 and let the samples of h(n) by sual. The H(w) can be vertuented as magnitude & phase function as $H(w) = \pm |H(w)|_{e} j^{o}(w) = 0$ Job Symmetric and Arti-symmetric filter Equating real & imaginary parts, $\sum_{n \geq 0} h(n) \left((\omega_n \omega_n - j \sin \omega_n) \right) = \pm \left| H(\omega) \right| \left[(\omega_n \alpha \omega - j \sin \alpha \omega) \right]$ If h(n) is read their magnitude function is symmetric from (1) & (A). To get exactly linear phase Let b(n) be Phon N-1 h(n). e-jun = + |H(w) | e-jalo H(w) = # |H(w) = jaw $\pm |H(\omega)| \cos \alpha \omega = \sum_{n=0}^{N-1} h(n) \cos \omega n$ → |0(w) = - |0(-w)| function is and symmetric > |H(w) = |H(-w)|. H(w) = \sum_{n=0}^{N-1} h(n). e jun ___ ((a) = - am - (3) 10 (w) 0 w or Fourier transform of h(n) is





Pregnessy vesponer of linear phase FIR filling

Depending on the value of N (odd or ever) & Type of

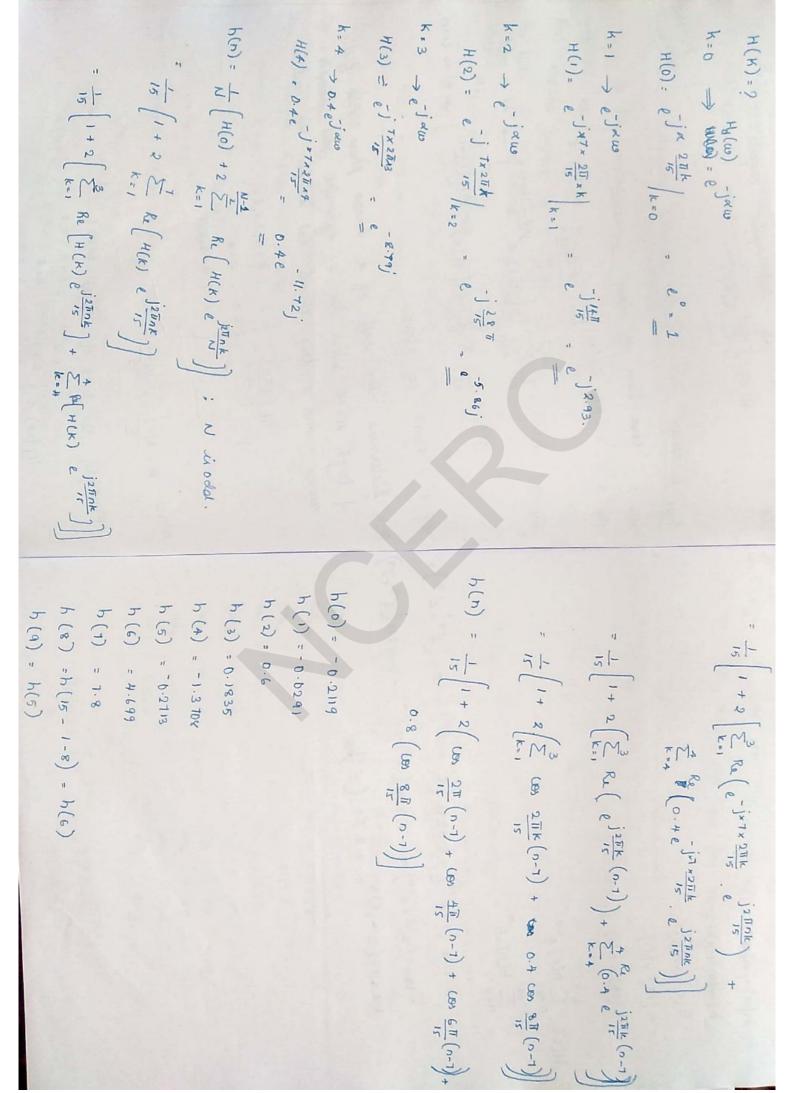
rymetry of filler impulse responer. Here are four possible

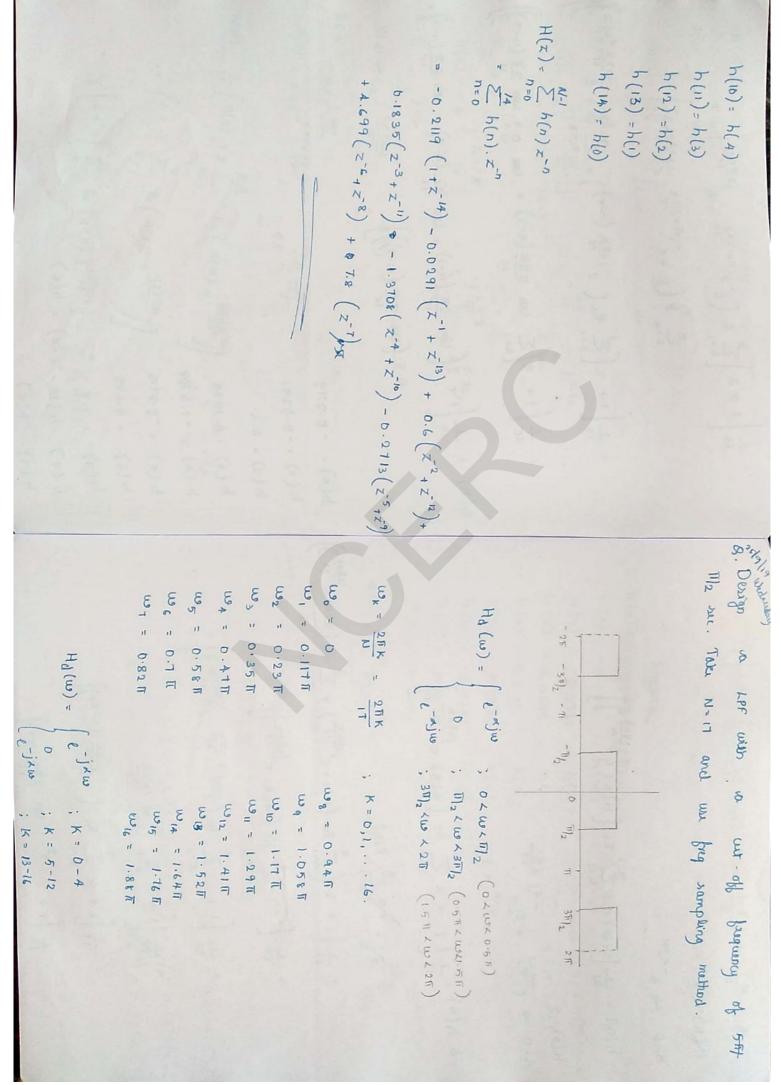
types of linear phase FIR fillers.

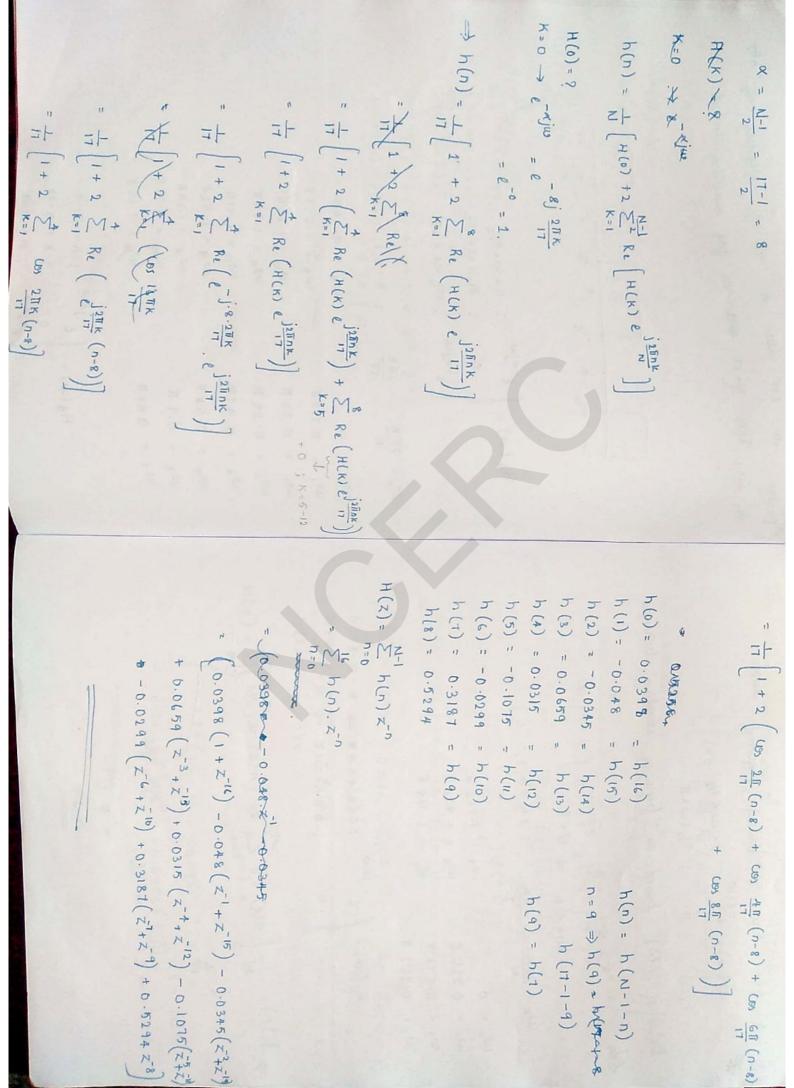
Symmetric impulse responer when N is odd.

2. symmetric impulse responer when N is ever,

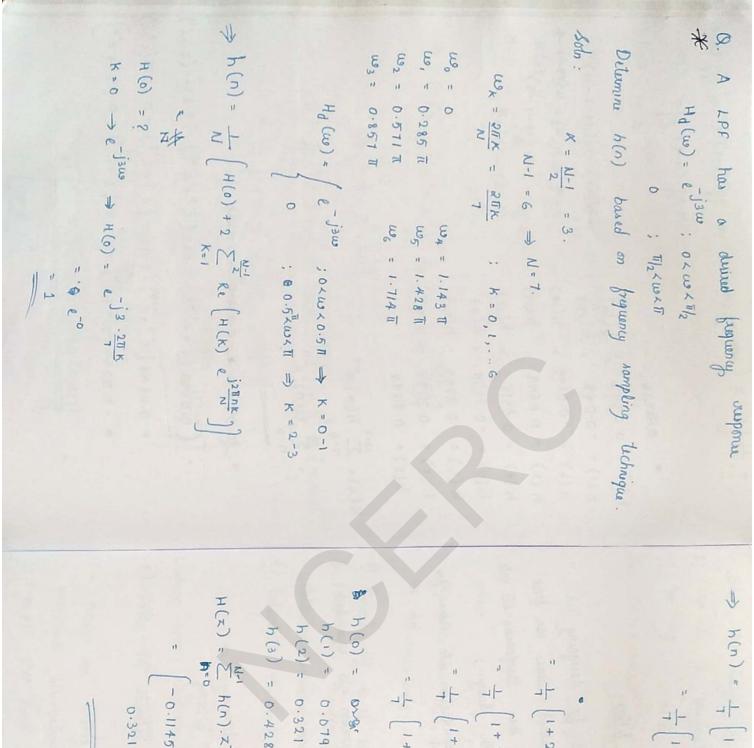
Alep 3: Compute h(n) using the following equation. $h(n) = \frac{1}{N} \left[H(0) + 2 \sum_{k=1}^{N-1} \text{Re} \left(H(K) e^{\frac{j 2 \pi n k}{N}} \right) \right] \rightarrow N \text{ is odd}.$ Truston Fraguency Sampling method Alp 1: Choose the ideal freq response Hollie) stip 2: Sample Hollis) at N points by taking w= wk = 211 k sufficient no. of points (N points). These samples are OFT wife of the impulse outpoone of the filler. Here the impulse appoint of Here, Hollie) = Ideal desixed freq response. the filter is adulesmired by Jaking the inverse DFT. 3. Anti-symmetrice impulse sesponse when N is odd $H(\kappa) = H_d(\omega) \Big|_{\omega = 2\pi\kappa}$ where K=0,1,2,3, N-1. To generate H(K). Arti-symmetric imputue susposous when is in even In this muthod, ideal frag response is sampled at H(k) - DFT signer obtained by sampling h(n) = impulse suspense of FIR filler. h(n) = 1 [H(0) + 2 \frac{N}{K=1} Re (H(K) e \frac{j 2 \text{Tink}}{N}]) \rightarrow N is even. Hd (m) $\frac{\lambda \text{Lip}}{N} \quad 3: \quad h(n) = \frac{2}{N} \sum_{k=0}^{N-3} \text{Re}\left(H(k) e^{jn\pi} \frac{(2k+1)}{N}\right) \rightarrow N \text{ is odd}.$ Q.1. Determine the well of a linear phase FIR filler step + same as above. λίφ 2: H(K)= Hd(ω) | ω= 2π (2κ+) $\frac{10 \text{ ln}}{2}$: $\frac{15-1}{2} = 1$ step 1: Gave Same as above Multiply the turns of Holes) with e-xju supone and a free surpone that solution the condition of longth N=15 which has a symmetric unit sample h(n) = 2 . 2 \sum_{k=0}^{H-1} Re[H(k), e^{jan(2k+1)}] \rightarrow N is even $H\left(\frac{2\pi K}{16}\right) = \begin{cases} 1 & \text{if } k = 0, 1, 2, 3 \\ 0.4 & \text{if } k = 4 \end{cases}$ $H(z) = \sum_{n=1}^{N-1} h(n) z^{-n}$ 0 ·; k=5,6,7.

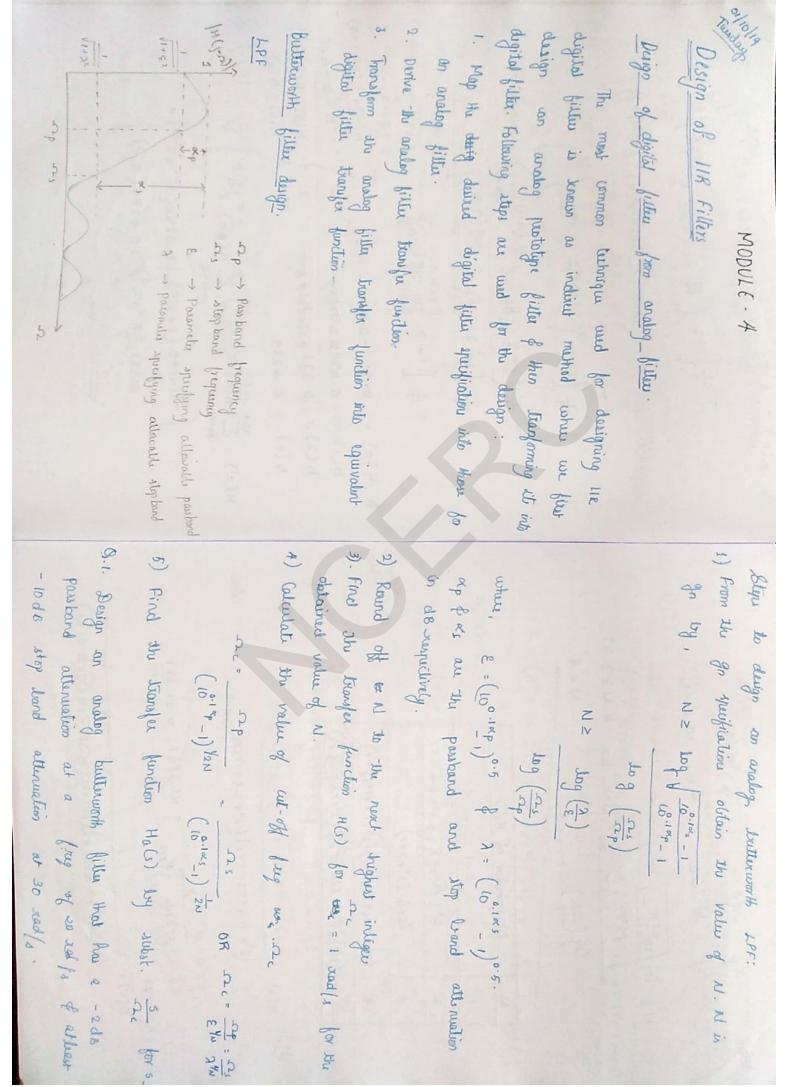


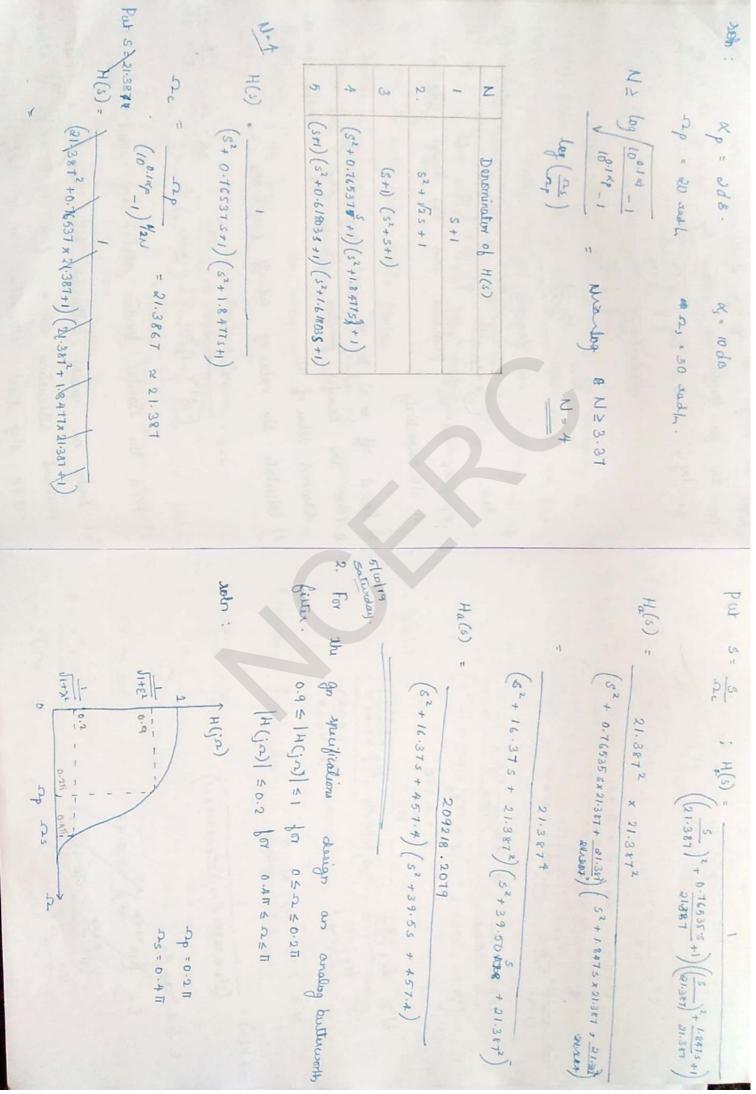


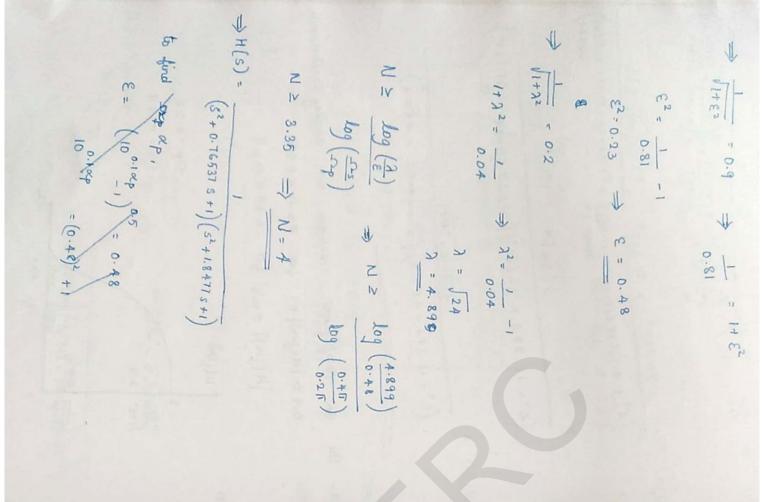


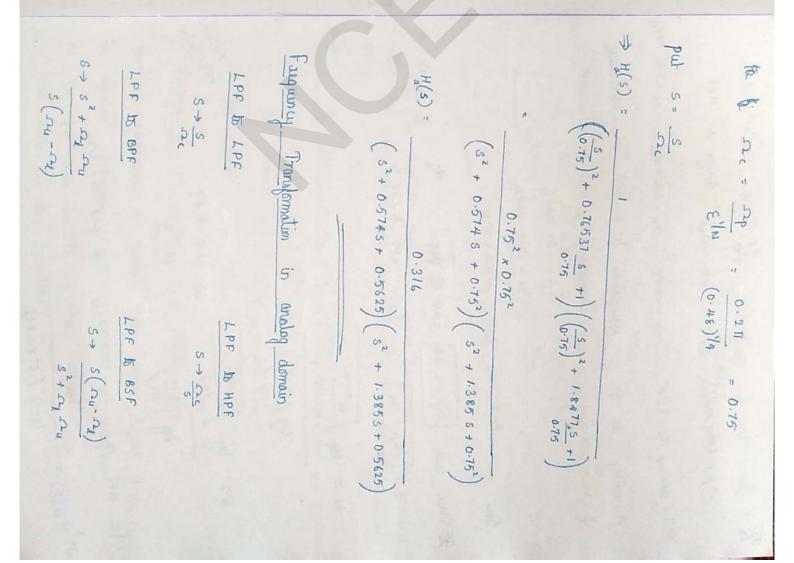
h (17-1-9)

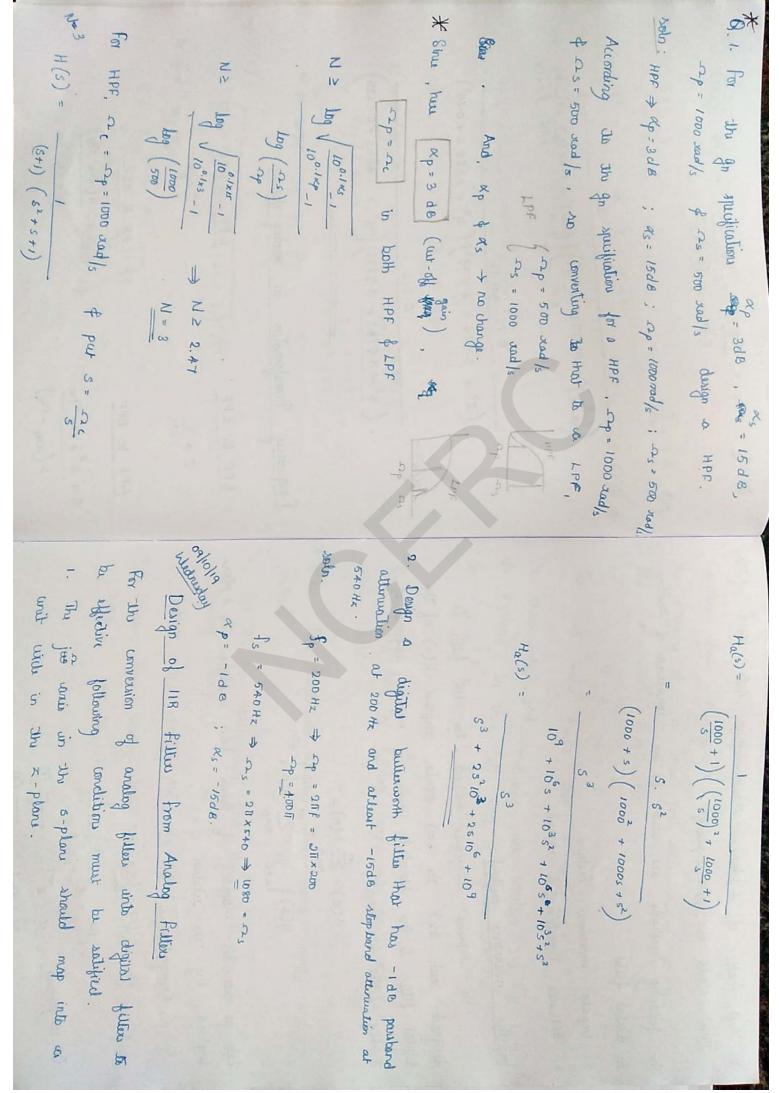




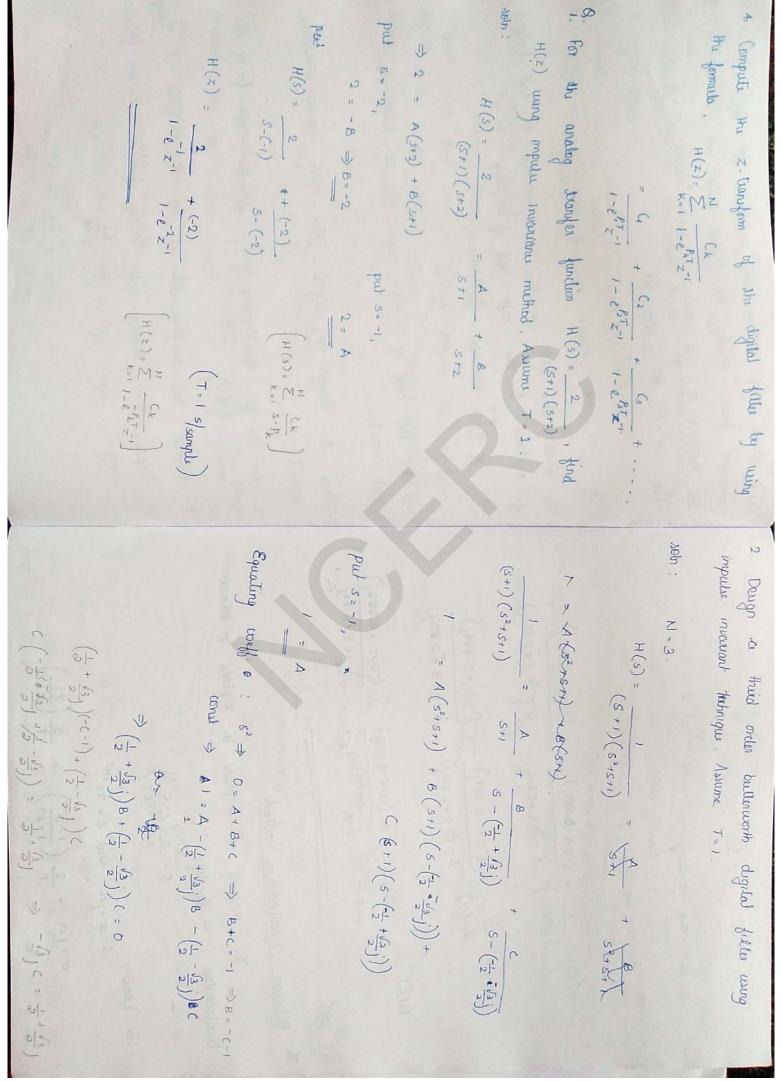


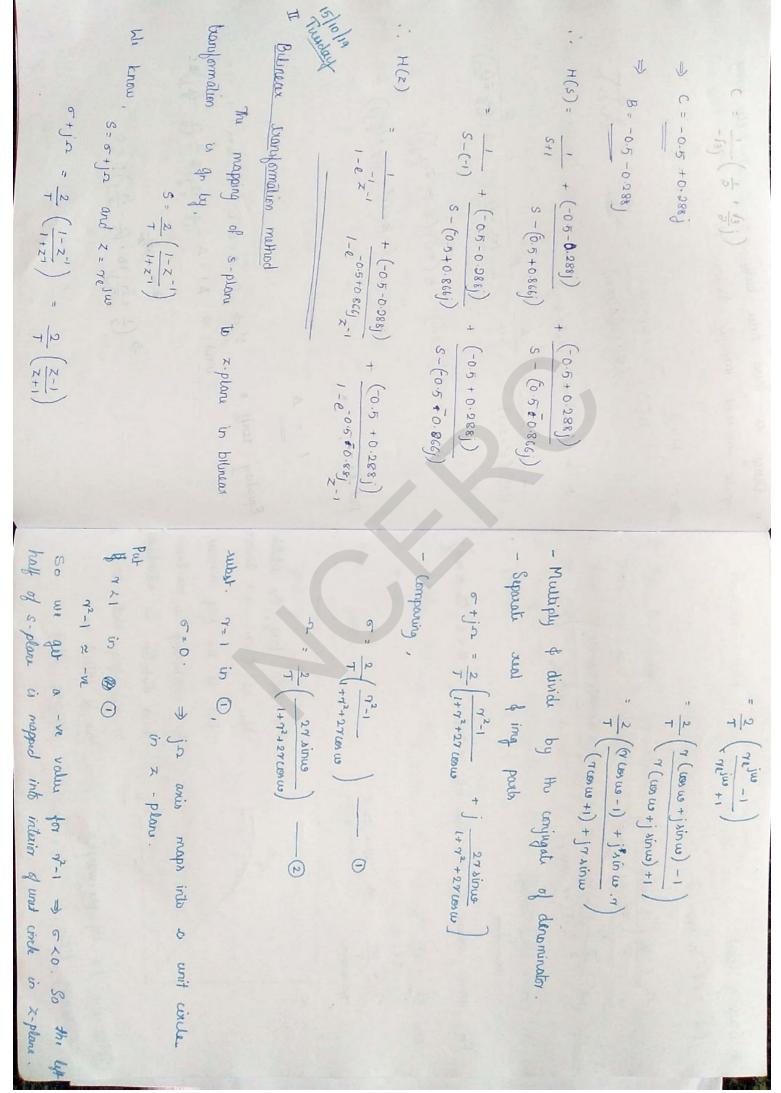


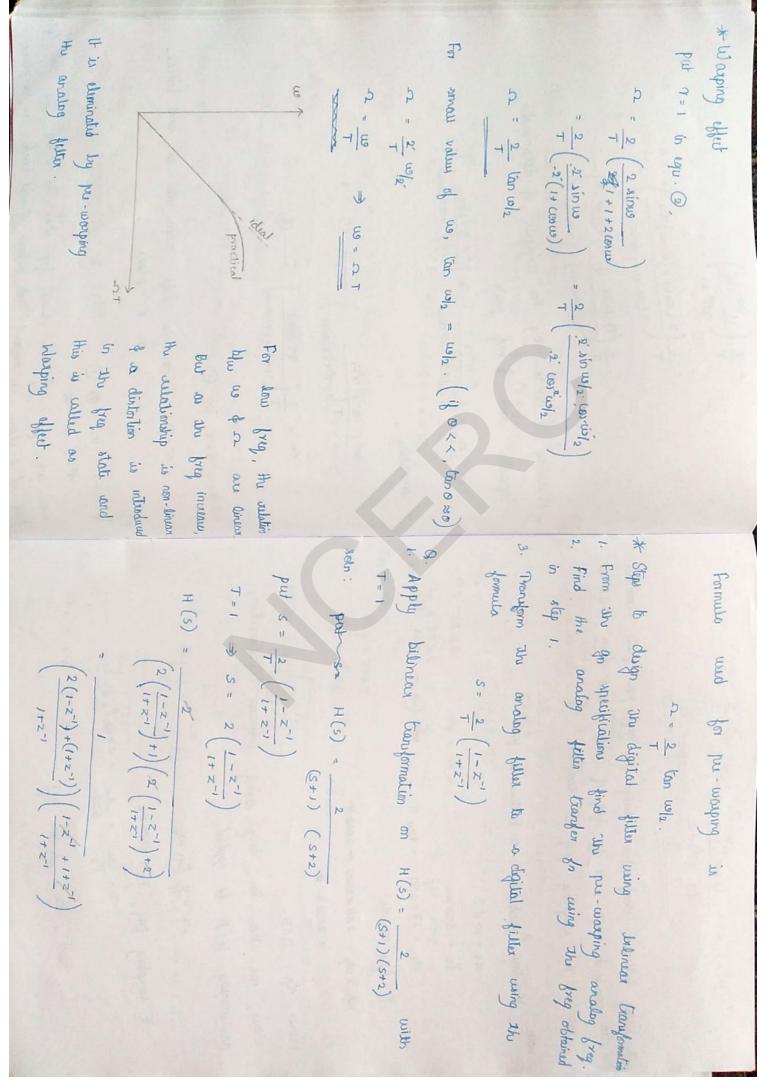


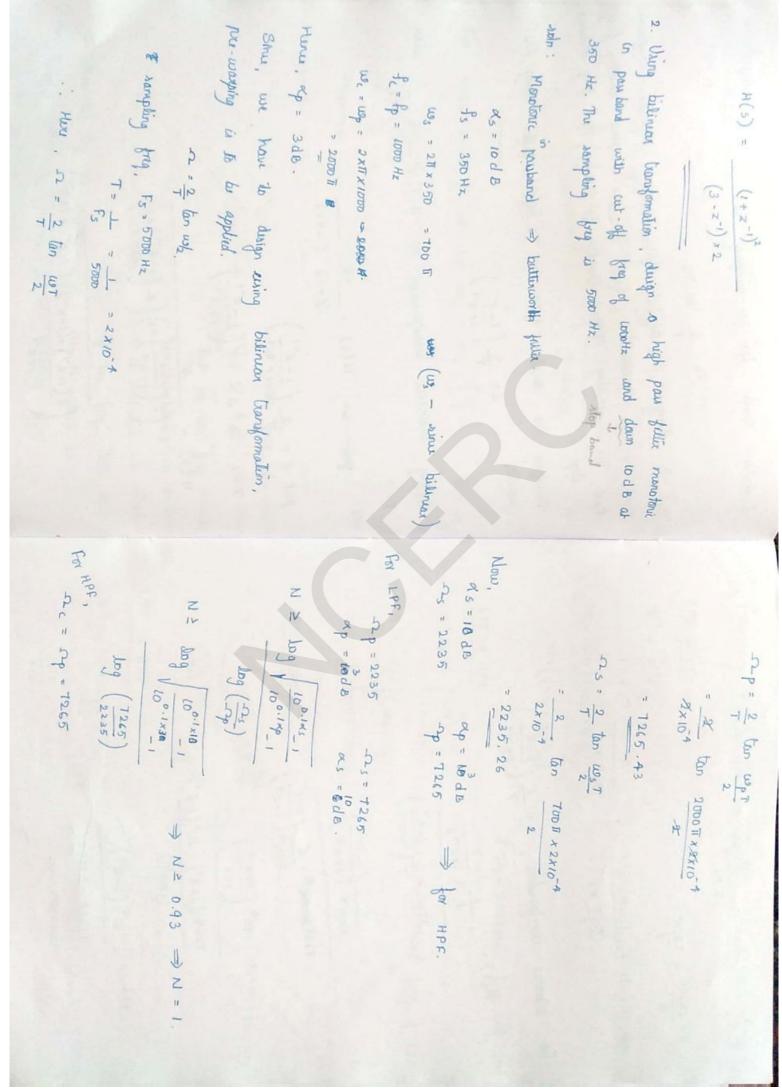


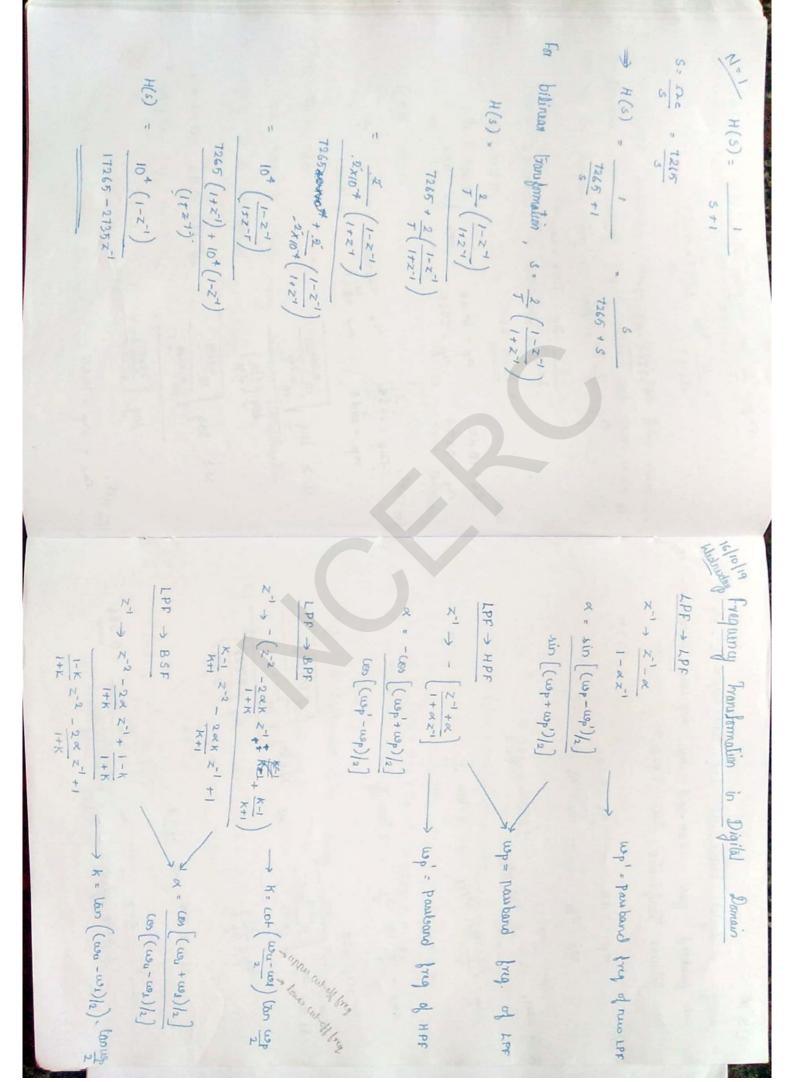
The following methods are used for the 2. Bilinax Garyformation muthod 2. Left half of s-plane should impulse invaviance method for truckers reproduce control of imborrer of respects designed such that the unit inputs suspense h(n) of the On compound, implied by the relation z = est Let us consider mapping of points analog filler. We know. But, s= s+ja + let z=40 jus Impulu invovanus method digular futur. with with in the z-plane. to impute invariance method, the like fitter is > rejus (o+ja)T reju = est ejat 7 = e ST H(z) $\Big|_{\chi=\ell^{ST}} = \sum_{n \in Q} .h(n) \ell^{-STn}$ H(x) = 56 h(n) z-n map from 5-plane to z-plane consum of analog into involve of the * Steps to design a digital fitter using impulse invasione To truck the a securities conditions for effective 1. For The go specifications find Hals) (transfer for of the of s-plane. In the left half of s-plane, or <0. To check the and condition we consider the left half So the left half of siplane maps into the interior of a unit with universion from analog to digital fitter, we first consider He mapping of ja ancio. ja ancio means o=0 Put or = 0 in equ. 0 Eachren Sected the sampling vate of the digital filler - T strangle World . galano Ja ancis maps unto a unit wide. e e st becomes (-ve) value <1 1=v = 0 = n=1 the analog filler transfer function in the following filler) 5-8

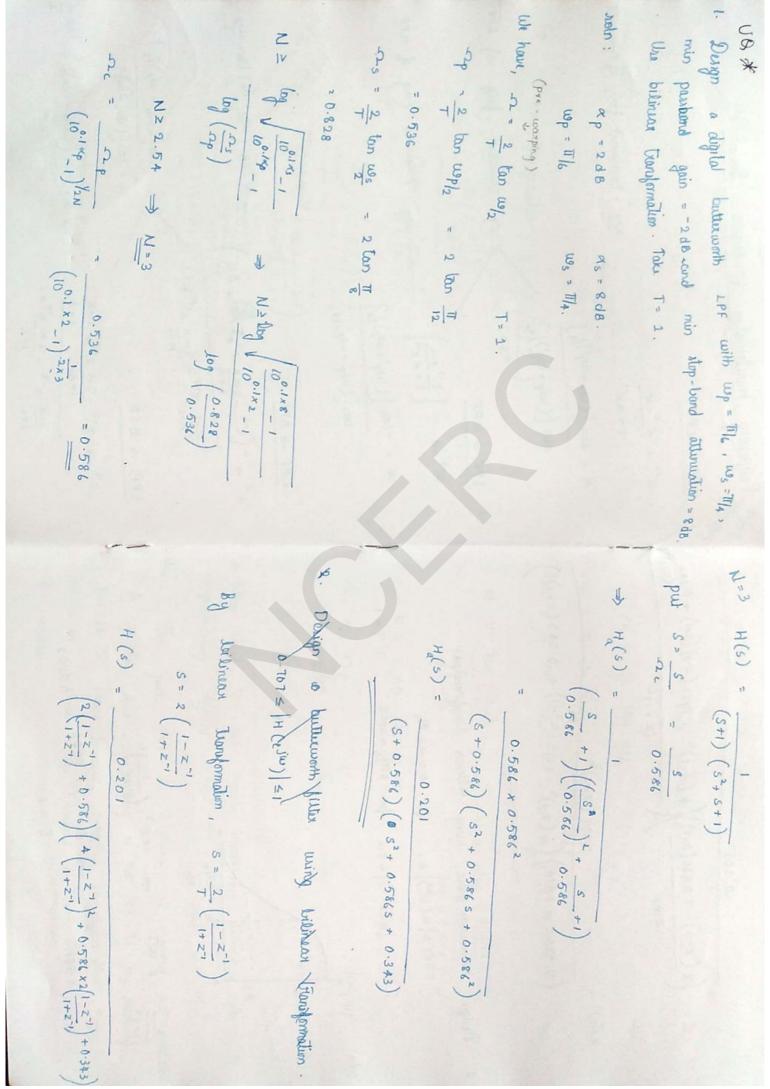


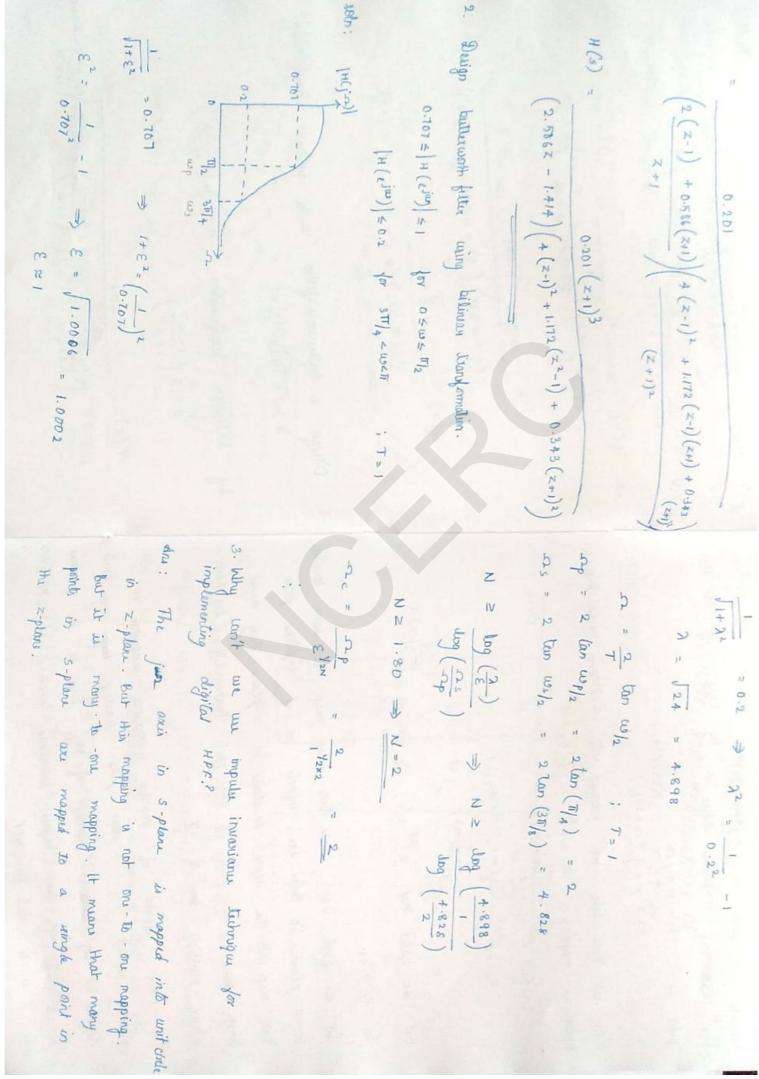












only. It is not used for HPF. invariance mapping Z, = e S,T & Z2 = e SxT Now, let these pulse be mapped into z-planes using impulse The main disade of impulse invaviance mapping is Consider a pole in s-plane with identical real points so we find that there are, infinite no of s-plane poles of aliasing we we impulse invavians method for LPF & 895, difference in by integral multiple of 2011. Due to the present aliasing laused by 5-plan poles having time ing. parts integer multiple by of 217. that map into the same locations in z-plane. They must but with ing umpounts differ in by 211/T. So let the have some real parts & ing parts that differ by some ないな。 we know that ejal = 1, 80 Z1 = e SIT = ((0+j.1)) T S1 = 9+ ja S2 = 0+ j (2+2T/T) (((+) (a+ 2 //)) T = (6+1-2)7 1 28 Z2 = e (0+ja) T

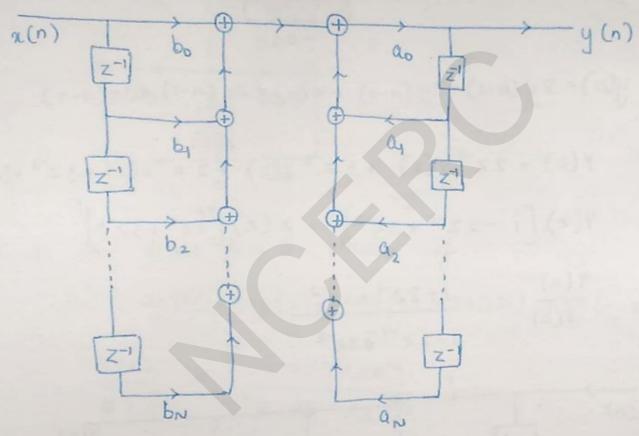
22 Transpart.

MODULE-5

STRUCTURES FOR REALISATIONS OF DIGITAL FILTERS

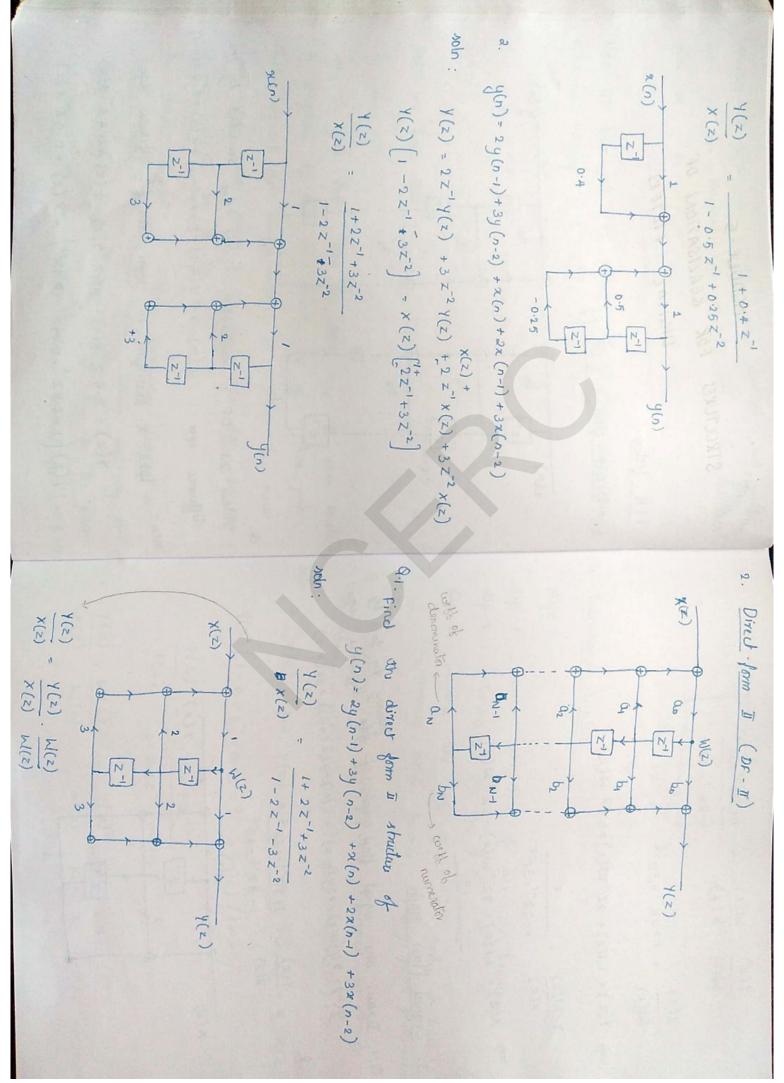
11R filters

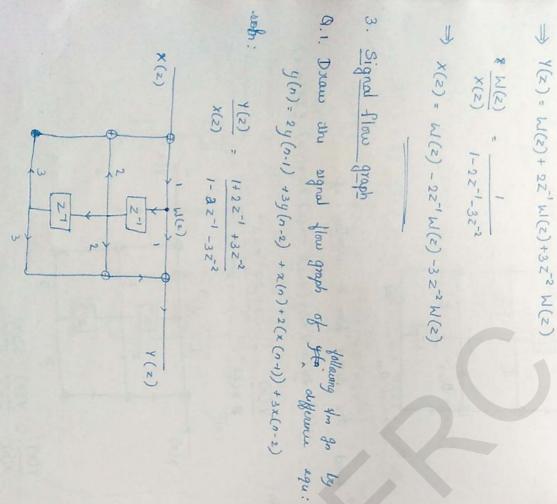
1. Direct - form I (DF-I)

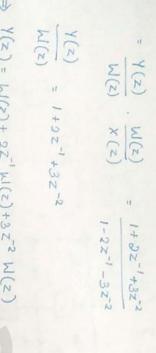


de difference equ. : y(n)=0.5y(n-1)-0.25y(n-2)+x(n)+0.4x(n-1)

Note: Take z. transform on both sides of $\frac{3}{2}$ difference equ. $Y(z) = 0.5 z^{-1} Y(z) - 0.25 z^{-2} Y(z) + x(z) + 0.4 z^{-1} X(z)$ $Y(z) \left[1 - 0.5 z^{-1} + 0.25 z^{-2} + 0.4 z^{-2}\right] = x(z) + 0.4 z^{-1} x(z)$







Transposed struction

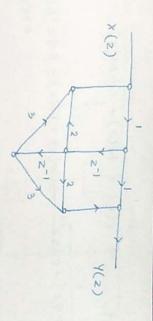
· relaye

9. 1. Determine the DF-II and transposed DF-II for step 1 : in of our of our the brancher. step 2: interchange the i/p, of o/pa atip 3: revere the votes of all the nodes in branche Mu shon y(n)= = = y(n-1) - + y(n-2) + x(n) + x(n-1) i.e., summing points becomes branching points of vice-versa

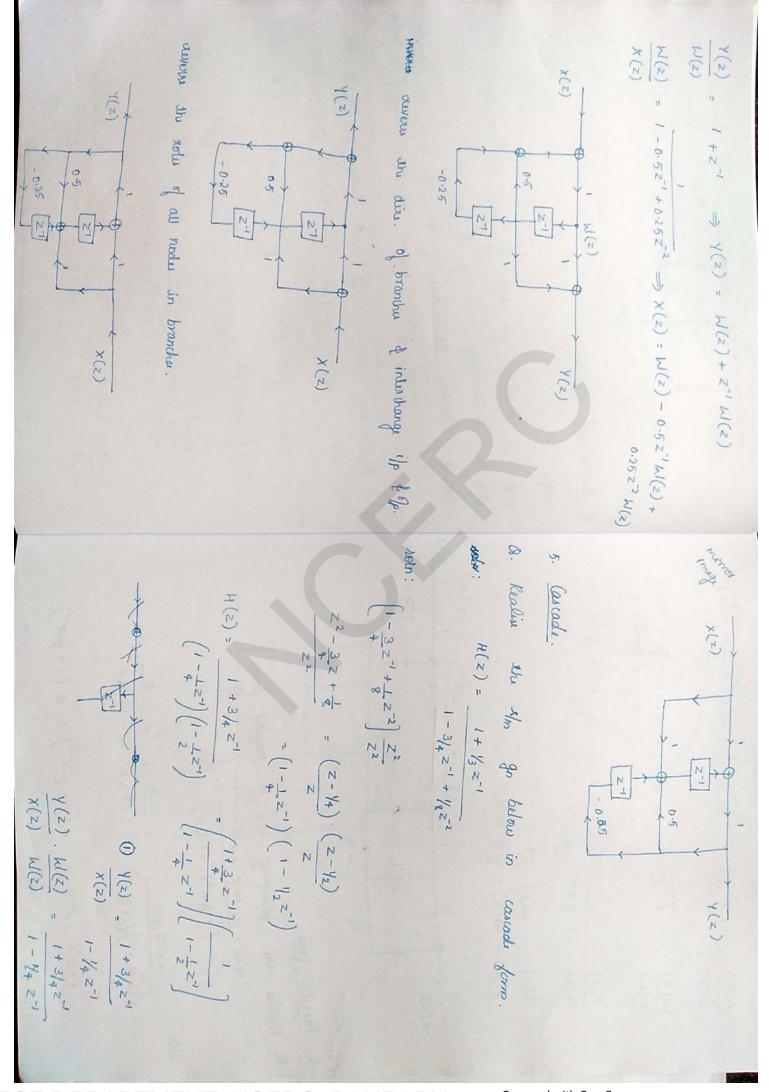
$$Y(z) \left[1 - 0.5z^{-1} + 0.25z^{-2} \right] = \chi(z) \left[1 + z^{-1} \right]$$

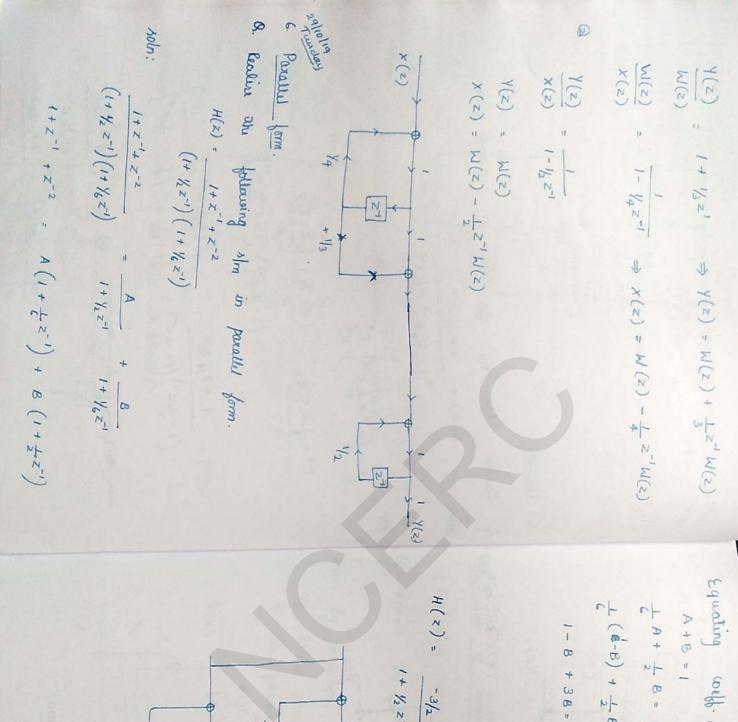
$$\frac{Y(z)}{\chi(z)} = \frac{1 + z^{-1}}{1 - 0.5z^{-1} + 0.25z^{-1}}$$

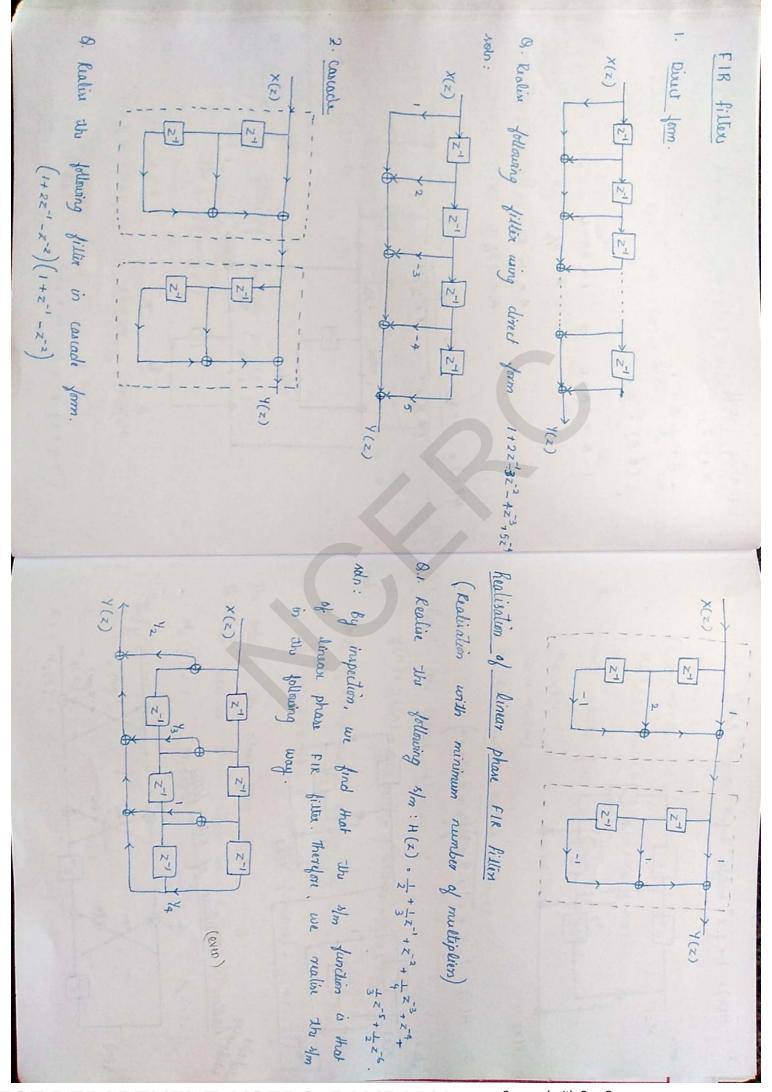
$$\frac{Y(z)}{\chi(z)} = \frac{Y(z)}{M(z)} = \frac{1 + z^{-1}}{M(z)} = \frac{1 + z^{-1}}{1 - 0.5z^{-1} + 0.25z^{-2}}$$

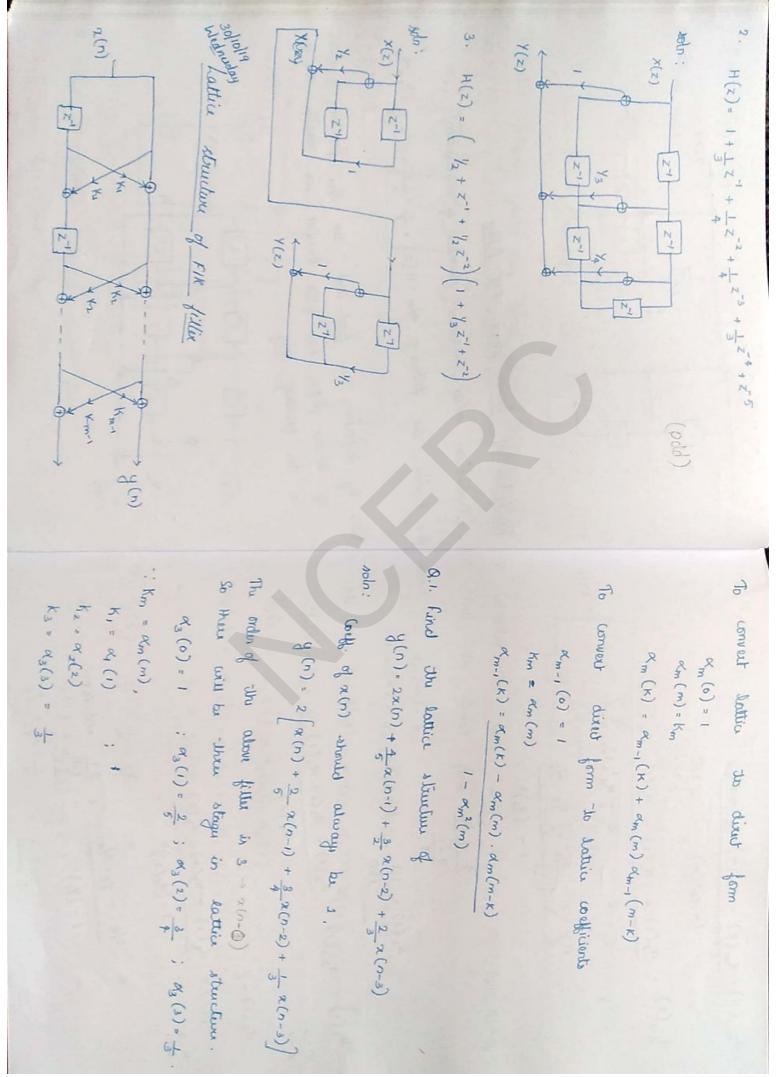


 $Y(z) = \frac{1}{2} z^{-1} Y(x) = \frac{1}{4} z^{-2} Y(z) + x(z) + x^{-1} x(z)$









$$\alpha_{n-1}(K) = \frac{\alpha_{lm}(K) - \alpha_{lm}(m) \cdot \alpha_{lm}(n-K)}{1 - \alpha_{lm}^{2}(m)}$$

$$\alpha_{1}(2) = \frac{\alpha_{2}(2)}{2} = \frac{\alpha_{3}(2) - \alpha_{3}(3) \cdot \alpha_{3}(3-2)}{8}$$

$$= \frac{3/4 - \frac{1}{3} \cdot \frac{2}{5}}{1 - (\frac{1}{3})^{2}}$$

$$= \frac{3}{4} - \frac{1}{15}$$

$$\frac{3}{4} - \frac{1}{15}$$

$$\alpha_{1}(1) = \frac{\alpha_{2}(1) - \alpha_{2}(1) \cdot \alpha_{3}(1)}{1 - \alpha_{2}^{2}(1)}$$

$$\alpha_{2}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(2)}{1 - \alpha_{3}^{2}(2)}$$

$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(2)}{1 - \alpha_{3}^{2}(3)^{2}}$$

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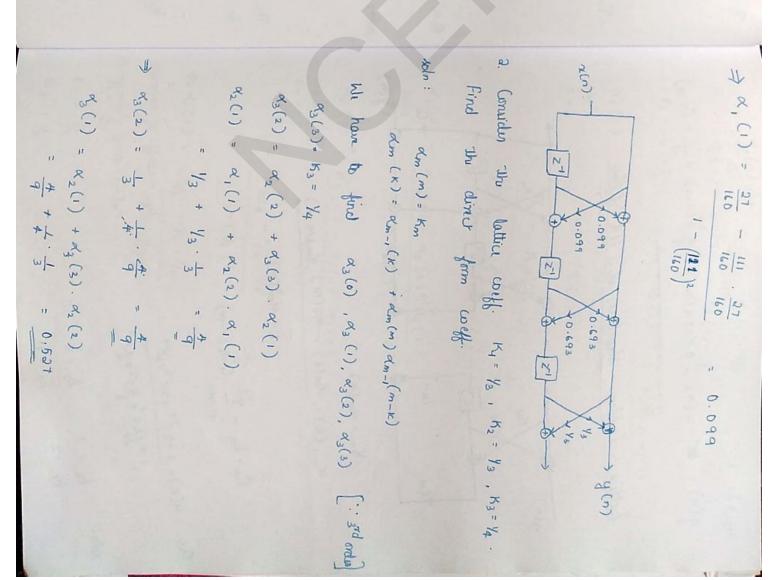
$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(3)}{1 - \alpha_{3}^{2}(3)^{2}}$$

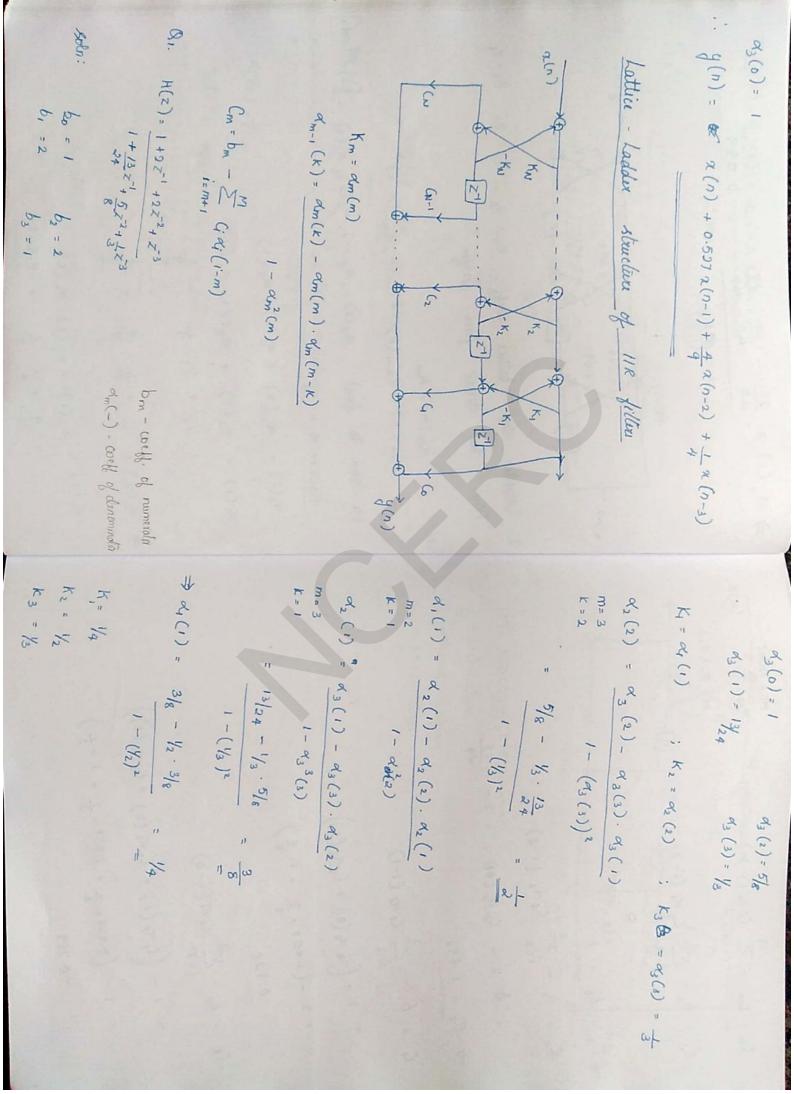
$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(3)}{1 - \alpha_{3}^{2}(3)^{2}}$$

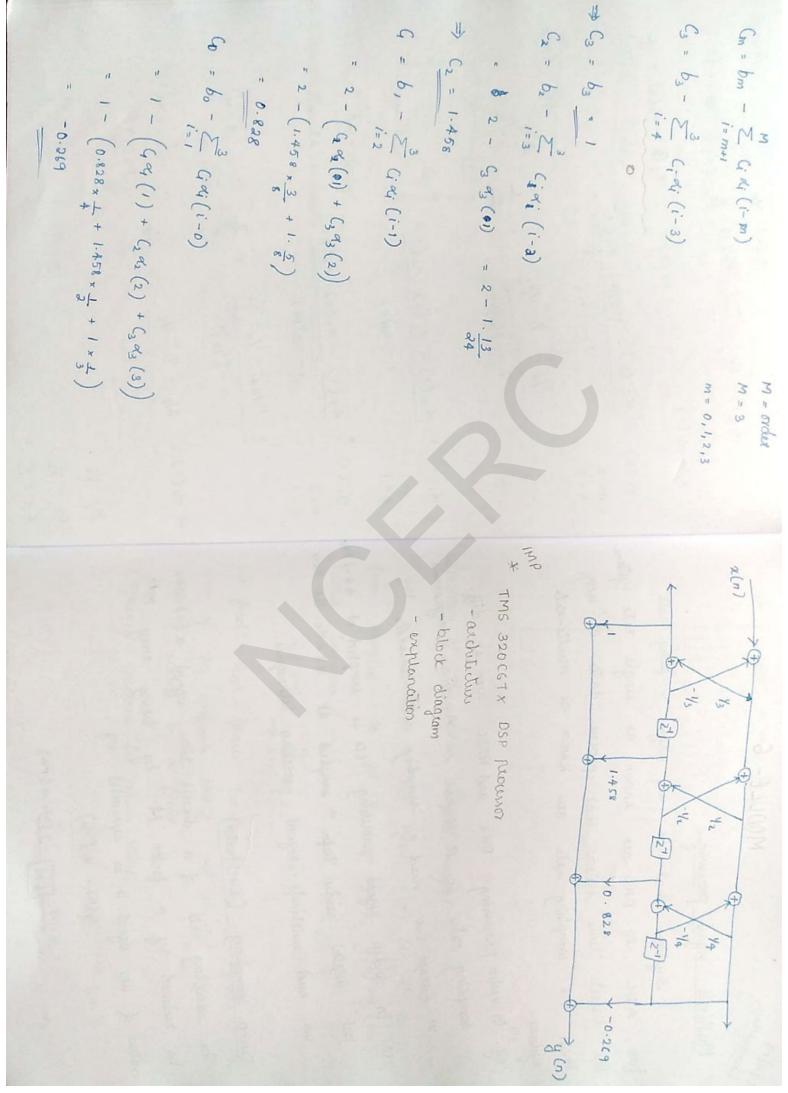
$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(3)}{1 - \alpha_{3}^{2}(3)^{2}}$$

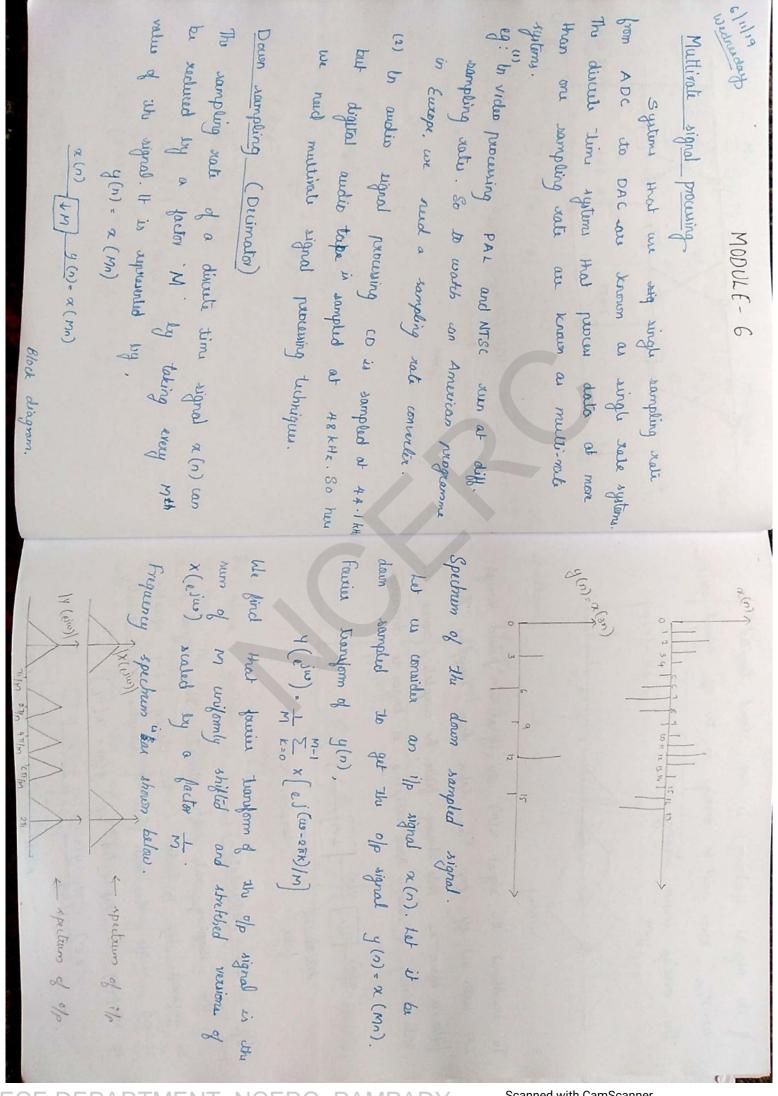
$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(3)}{1 - \alpha_{3}^{2}(3)^{2}}$$

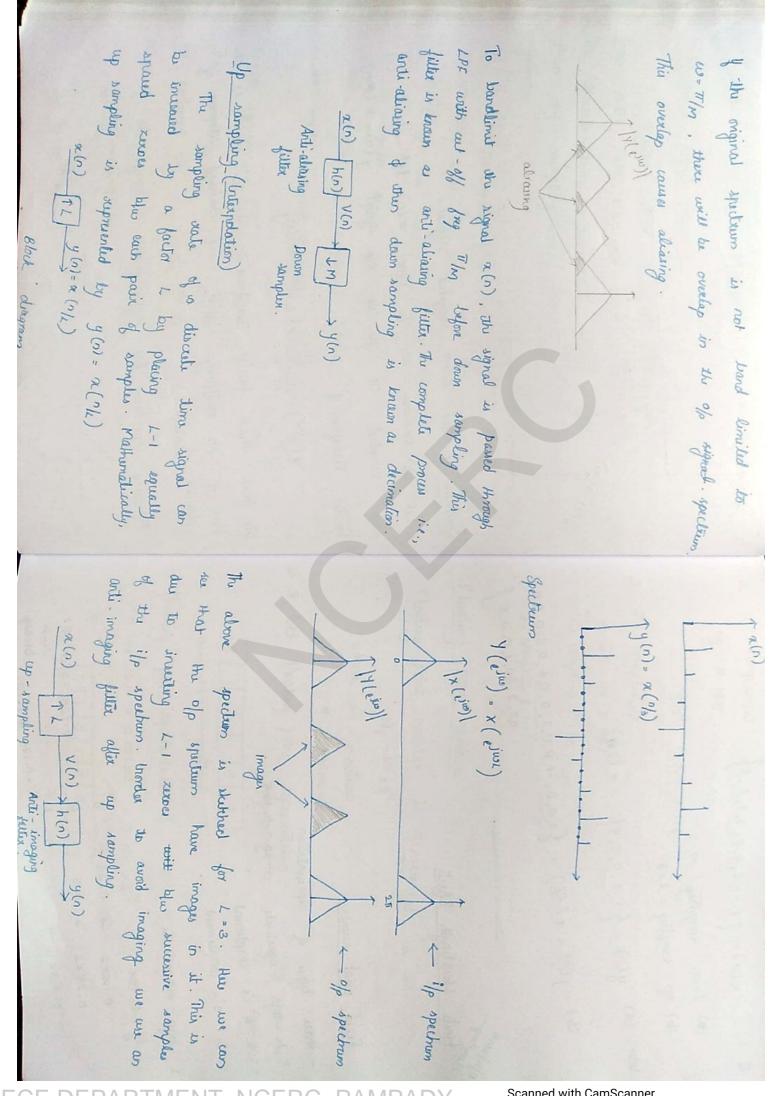
$$\alpha_{3}(1) = \frac{\alpha_{3}(1) - \alpha_{3}(3) \cdot \alpha_{3}(3)}{1 - \alpha_{3}^{2}(3)}$$

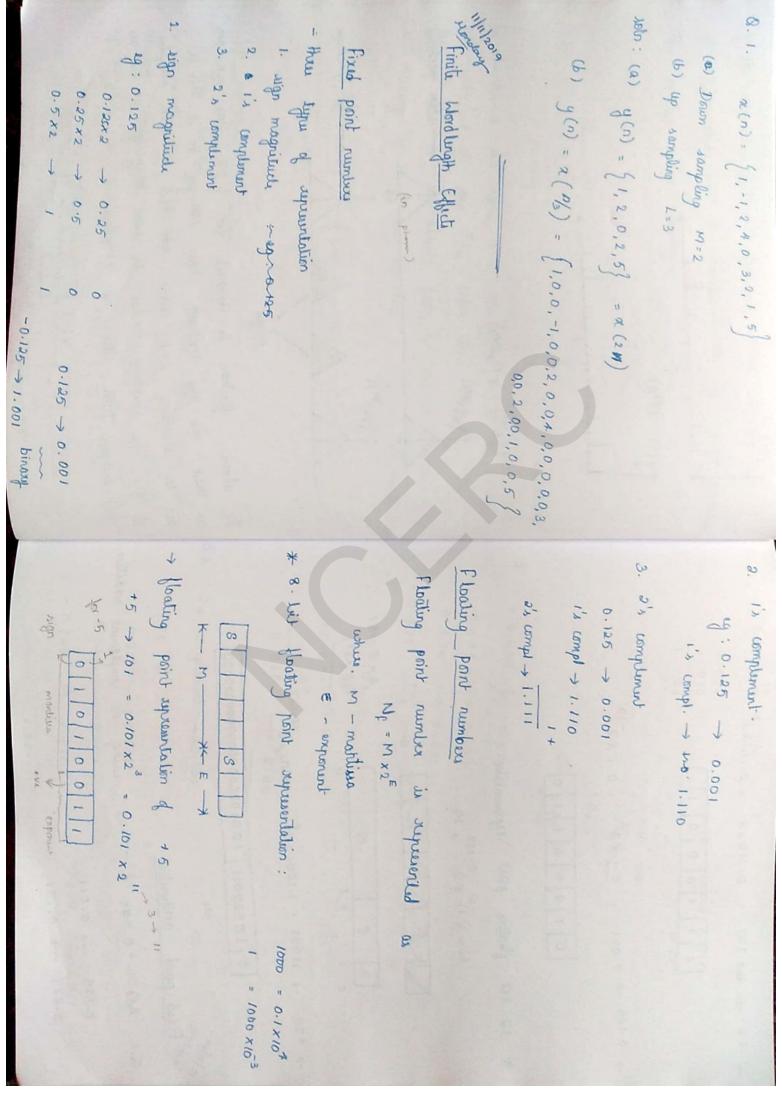


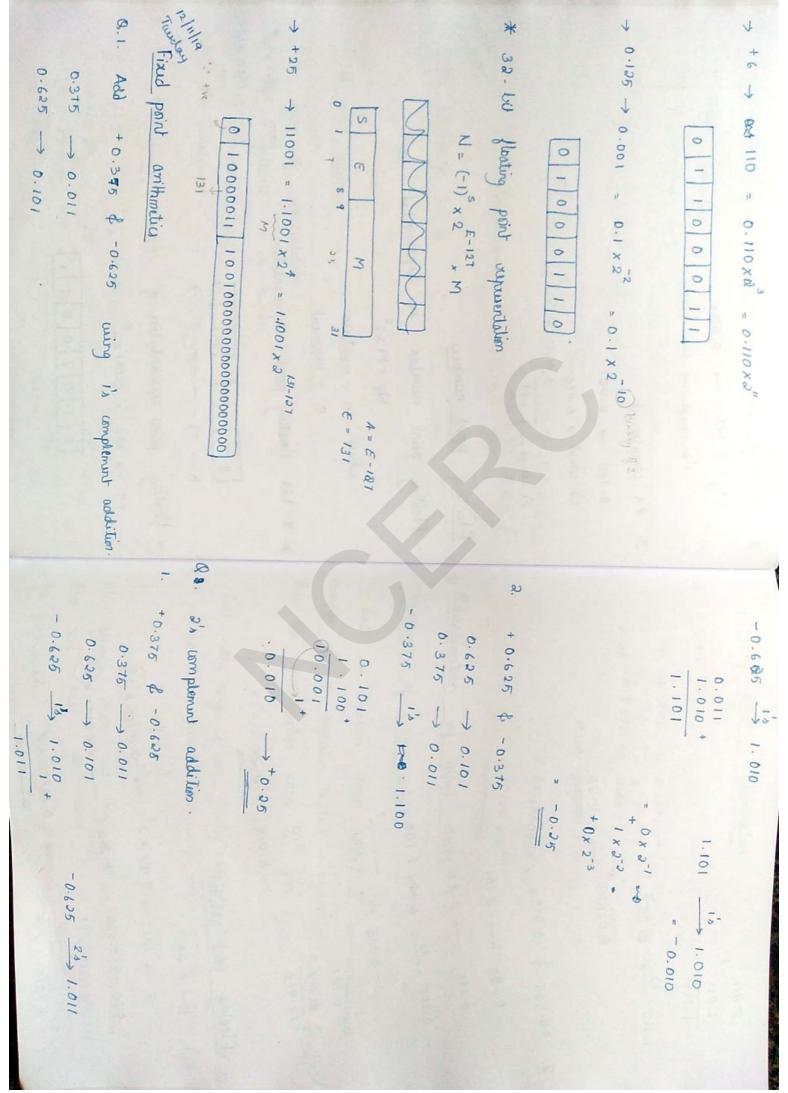


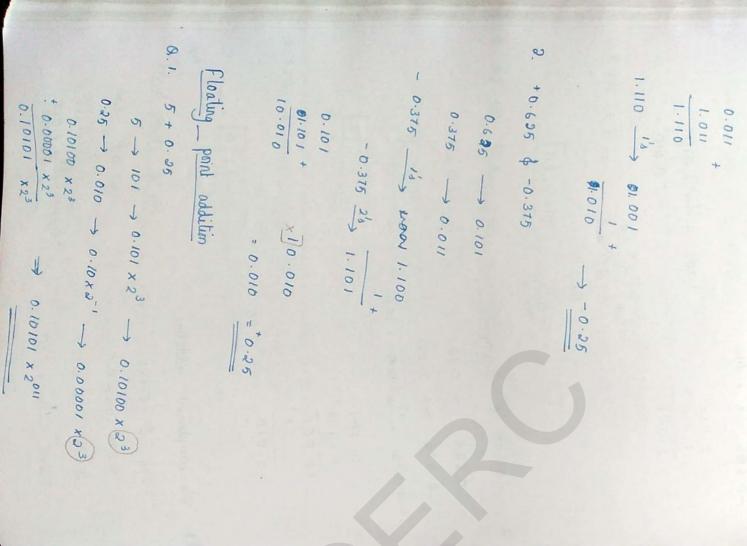




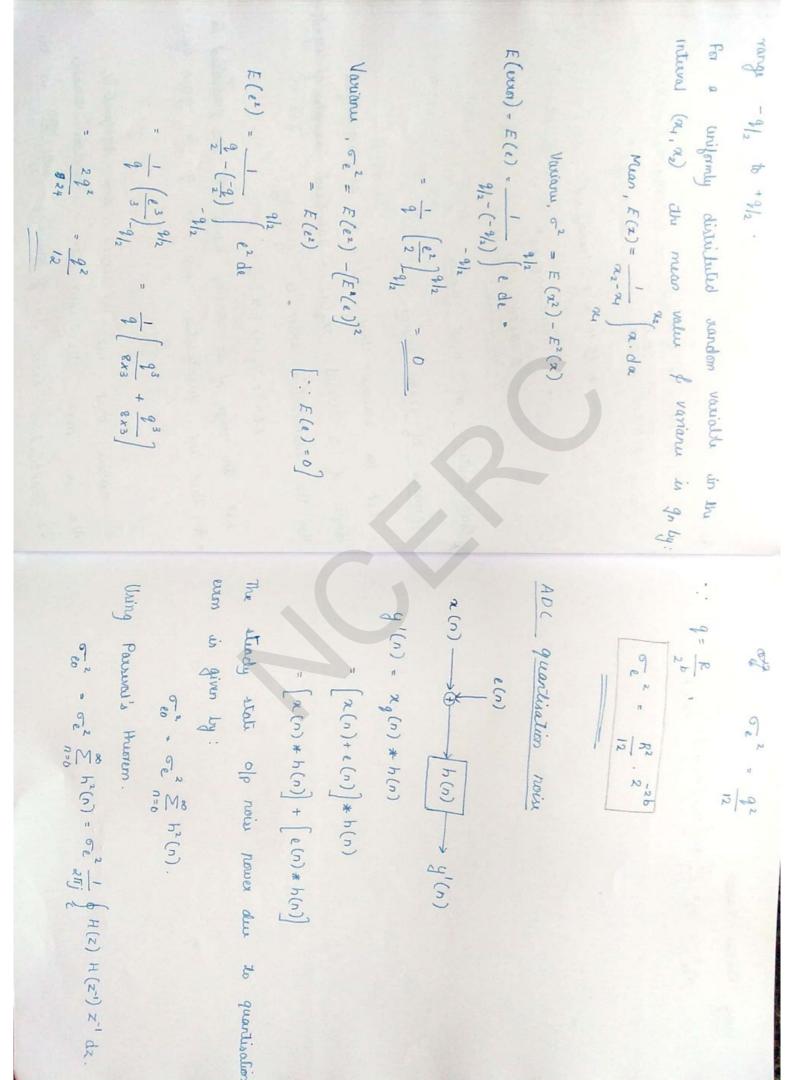


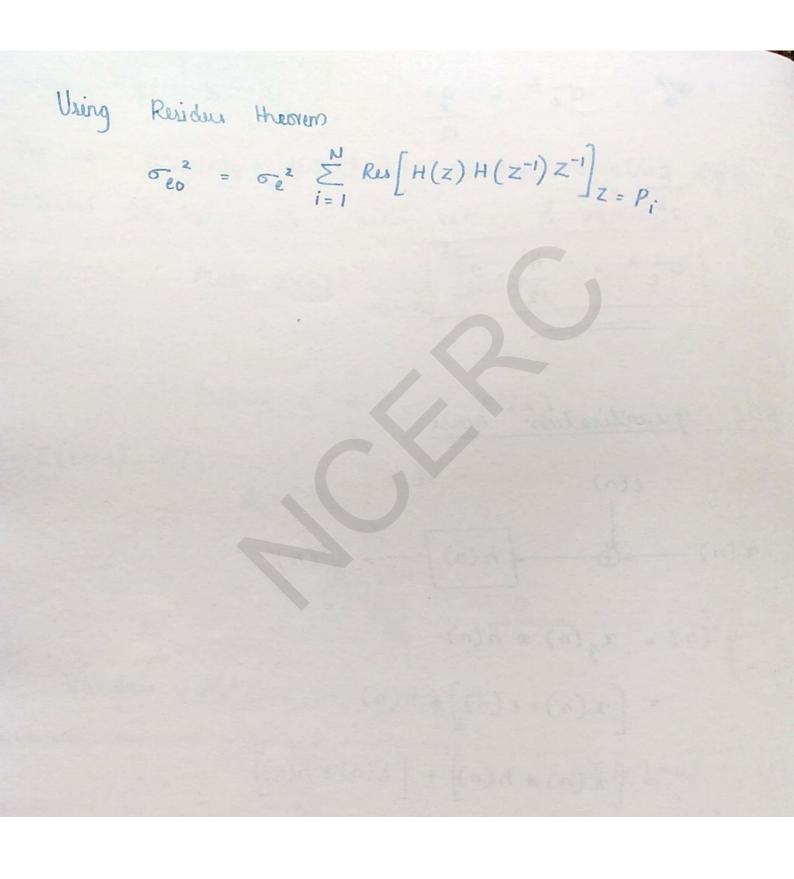


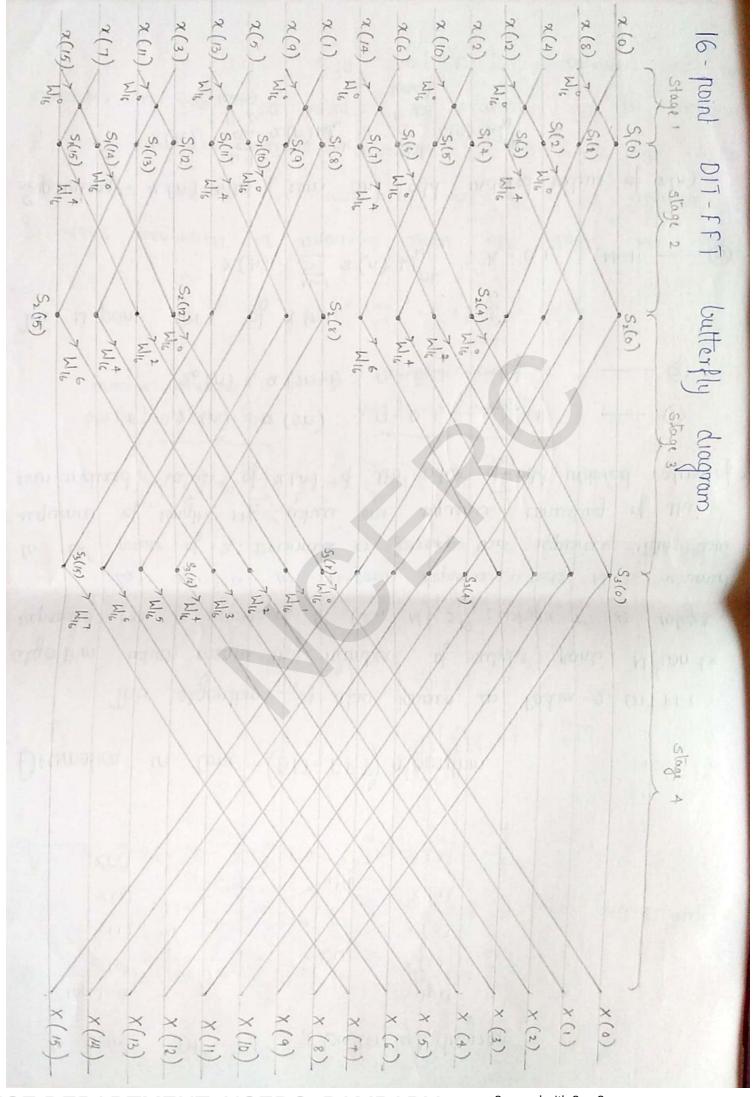


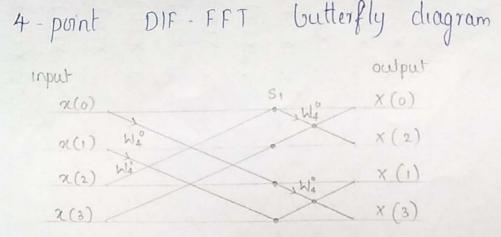


be R. Then the quantisation stop-ware q' is * Quantisation of input data 8 Thun the quantisation exern-is given by: sample of signal. sug(n) - quartised sample of signal. The quantisation exxor for & rounding will be in the Variance of exter signal. Let us assume that a (n) is an unquantised Flooting pant multiplication assume that all the extent are equipmebable. 5 x 0. 25 0.25 - 0.010 -> we treat the ever as a random variable. 5 -> 101 -> 0.101x23 The range of an analog signal e(n)= 2g(n) - 2(n). 9 = R ◆ (0.10100 x 0.10000) x 22 0.01010000000 x22 0.10100 x 2 001 0.10 0.10 0.10000 x2-1 -> 0.10100x33 (in ADC) be quantized & given by:









Decimation - in - time (DIT-FFT) algorithm

This algorithm is also known as Radix-2 DITFFT algorithm which means the number of output points N can be expressed as a power of 2 i.e., N = 2^M; where M is integer

Let x(n) is an N-point sequence, where N is assumed to be power of 2. Decimate or break this requerce into two sequences of length N/2, where one sequence consisting of the even-indexed values of x(n) of the other of odd-indexed values of x(n)

(.e,
$$\chi_{e}(n) = \chi(2n)$$
 ; $n = 0, 1, ..., \frac{N}{2} - 1$ — ①
 $\chi_{o}(n) = \chi(2n+1)$; $n = 0, 1, ..., \frac{N}{2} - 1$ — ②

The N-point DFT of a (n).

$$X(k) = \sum_{n=0}^{N-1} \alpha(n) W_N^{nk} ; k = 0, 1, ..., N-1$$
 3

Separating x(n) into even and odd indexed values of x(n), $x(k) = \sum_{n=0}^{N-1} x(n) \mathcal{W}_{N}^{nk} + \sum_{n=0}^{N-1} x(n) \mathcal{W}_{N}^{nk}$ (even) (edd)

$$= \sum_{n=0}^{\frac{N}{2}-1} \chi(2n) W_{N}^{2nk} + \sum_{n=0}^{\frac{N}{2}-1} \chi(2n+1) W_{N}^{(2n+1)k}$$

$$= \sum_{n=0}^{\frac{N}{2}-1} \chi(2n) W_{N}^{2nk} + W_{N}^{k} \sum_{n=0}^{\frac{N}{2}-1} \chi(2n+1) W_{N}^{2nk} - 3$$

$$X(k) = \sum_{n=0}^{\frac{N}{2}-1} \chi_{e}(n) W_{N}^{2nk} + W_{N}^{k} \sum_{n=0}^{\frac{N}{2}-1} \chi_{o}(n) W_{N}^{2nk} - 6$$

hle have

$$W_{N}^{2} = \left(e^{-j\frac{2\pi}{N}}\right)^{2}$$

$$= \left(e^{-j\frac{2\pi}{N}}\right)^{2} = \left(e^{-j\frac{2\pi}{N}}\right)^{2}$$

$$X(K) = \sum_{n=0}^{\frac{N}{2}-1} \alpha_{e}(n) W_{N|_{2}}^{nk} + W_{N}^{k} \sum_{n=0}^{\frac{N}{2}-1} \alpha_{o}(n) W_{N|_{2}}^{nk}$$

$$N|_{2} - point DFT of even \qquad N|_{2} - point DFT of odd$$

$$Indexed sequence \qquad included sequence$$

$$X(K) = X_e(K) + W_N^k X_o(K)$$

Now we apply the same approach to decompose each of $\frac{N}{2}$ sample DFT. This can be done by dividing the sequence $x_{e}(n)$ and $x_{o}(n)$ into 2 sequences consisting of even & odd members of the sequences. The $\frac{N}{2}$ point DFTs can be expressed as a combination of $\frac{N}{4}$ point DFTs.

i.e.,
$$\chi_{e}(k) = \chi_{ee}(k) + W_{N}^{2k} \chi_{eo}(k)$$
; $0 \le k \le \frac{N}{2} - 1$

$$= \chi_{ee}(k - \frac{N}{4}) - W_{N}^{2(k - \frac{N}{4})} \chi_{eo}(k - \frac{N}{4}); \frac{N}{4} \le k \le \frac{N}{2} - 1$$

where $X_{ee}(k)$ is $\frac{N}{4}$ point DFT of the over mambers of $\alpha_e(n)$ and $X_{eb}(k)$ is $\frac{N}{4}$ point of DFT of the odd members of $\alpha_e(n)$ in the same way,

$$X_{0}(k) = \chi_{0e}(k) + W_{N}^{2k} \chi_{0b}(k)$$
; $0 \le k \le \frac{N}{2} - 1$

$$= \chi_{0e}(k - \frac{\mu}{4}) - W_{N}^{2(k - N/4)} \chi_{0b}(k - \frac{N}{4})$$
; $\frac{N}{4} \le k \le \frac{N}{2} - 1$

where $X_{0e}(k)$ is $\frac{N}{4}$ point of DFT of the odd members of $x_0(n)$ and $x_{0e}(k)$ is $\frac{N}{4}$ point of DFT of the odd members of $x_0(n)$

Decimation in - frequency algorithm

DFT computation by forming smaller and smaller subsequences of the sequence $\alpha(n)$ in DIF algorithm the output sequence $\alpha(n)$ is divided into smaller $\alpha(n)$ is partitioned into two sequences each of length $\frac{N}{2}$ samples. The first sequence $\alpha_{2}(n)$ consists of that $\frac{N}{2}$ samples of $\alpha(n)$ and the second sequence $\alpha_{2}(n)$ consists of the last $\frac{N}{2}$ samples of $\alpha(n)$.

i.e.,
$$\alpha_1(n) = \alpha(n)$$
; $n = 0, 1, 2, ..., \frac{N}{2} - 1$ — ①
$$\alpha_2(n) = \alpha(n + \frac{N}{2}); n = 0, 1, 2, ..., \frac{N}{2} - 1$$
 — ②

When
$$k$$
 is even, $e^{-j\pi k} = 1$.

$$X(n) = 8 \text{ the first sequence} \quad x_1(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_2(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has } \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n) \text{ has values for } 0 \le n \le 3 \text{ degree} \quad x_3(n)$$

where $f(n) = [x_1(n) + x_2(n)]$

Equ. 3 is the $\frac{N}{2}$ point DFT of the $\frac{N}{2}$ point sequence f(n) obtained by adding the first half & the last half of the input sequence. When k is odd, $e^{-j\pi k} = -1$ $X(2k+1) = \sum_{n=0}^{N} [x_1(n) - x_2(n)] W_N$

 $= \sum_{n=1}^{\frac{N}{2}-1} f(n) W_{N_{12}}^{nk}$

(3)

$$\chi(2k+1) = \sum_{n=0}^{\frac{N}{2}-1} g(n) W_{N_{2}}^{nk} \qquad - \Phi$$
where $\int_{0}^{\infty} g(n) = \left(\alpha_{1}(n) - \alpha_{2}(n)\right) W_{N}^{n}$

Equ. (A) Us the $\frac{N}{2}$ point DFT of the sequence g(n) obtained by subtracting the second half of the input sequence from the first half and then multiplying the xeculting sequence with W_N^2 .